6.1800 Spring 2025

Lecture #3: Virtual Memory

how does it work, but more importantly, why does an OS use it?

6.1800 in the news

caveat: this does not appear to be a large-scale measurement study, we should not draw huge conclusions about the performance of Tubi vs. YouTube TV from these results alone

We measured latency against the over-the-air (OTA) broadcast the local San Francisco Fox affiliate KTVU delivered. Although our TV supports NextGen TV and KTVU broadcasts a NextGen signal we stuck with the regular ATSC 1.0 broadcast.[i] Note that the TV broadcast is delayed behind the actual live game.

The Tubi stream was consistently at or slightly ahead of the OTA. The Tubi browser was three or more seconds ahead, while the connected TV app was about a second behind. Even T-Mobile's network delivered slightly ahead of the OTA broadcast. These delays are very small, and stream viewers had no reason to worry about social media posts calling a play before they had seen it.

	Tubi	Tubi Mobile	YouTube TV	Tubi Browser	Tubi CTV
1st Quarter					
Delay	-3.2	4.4	35.3	-5.5	
Start Time	2	9.9	1.9	1.7	
2nd Quarter					
Delay	0	1	30.1	-7	
Start Time	7.3	27.9	2	1.5	
3rd Quarter					
Delay	-2.5	-4.5	29.9	-5.5	2
Start Time	7.4	25	2.2	1.7	5.5
4th Quarter					
Delay	-0.5	-2.3	31.4	5	0.5
Start Time	3	17.5	3	7	3

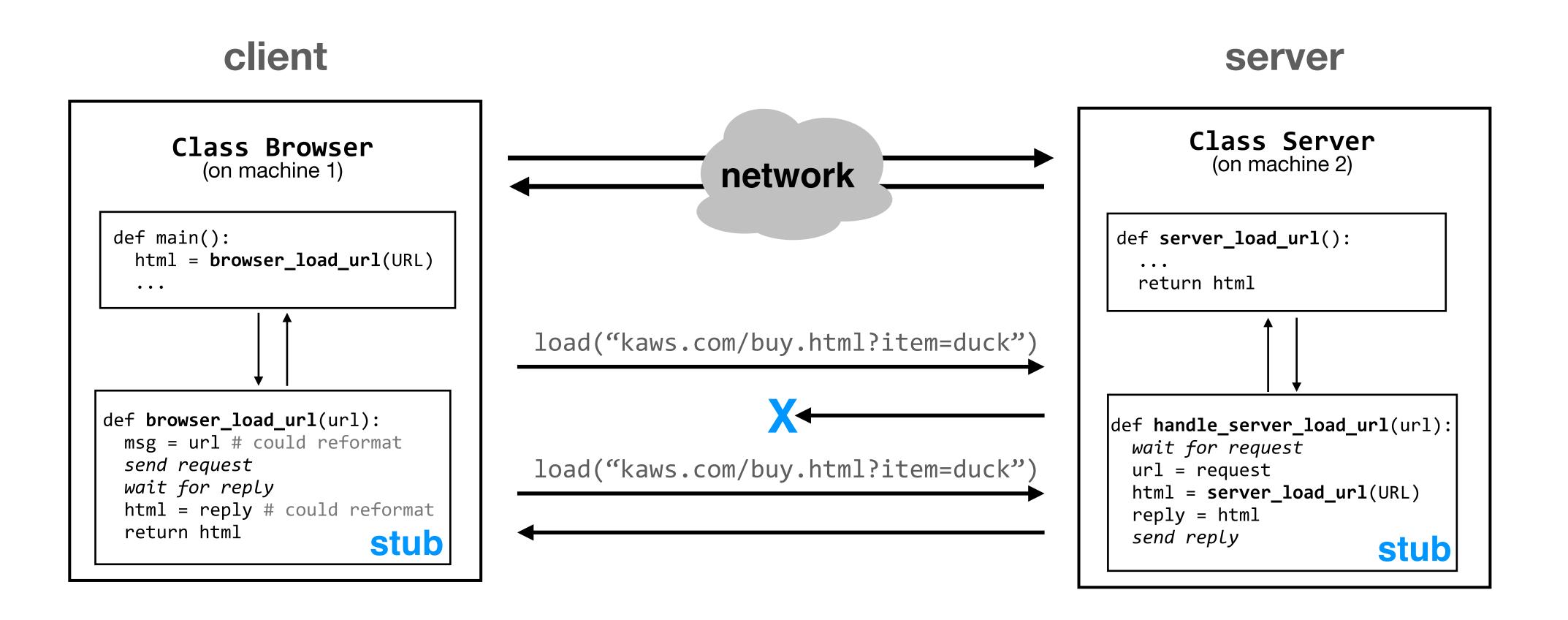
All times are seconds. Delay is relative to local TV over-the-air broadcast

Source: nScreenMedia

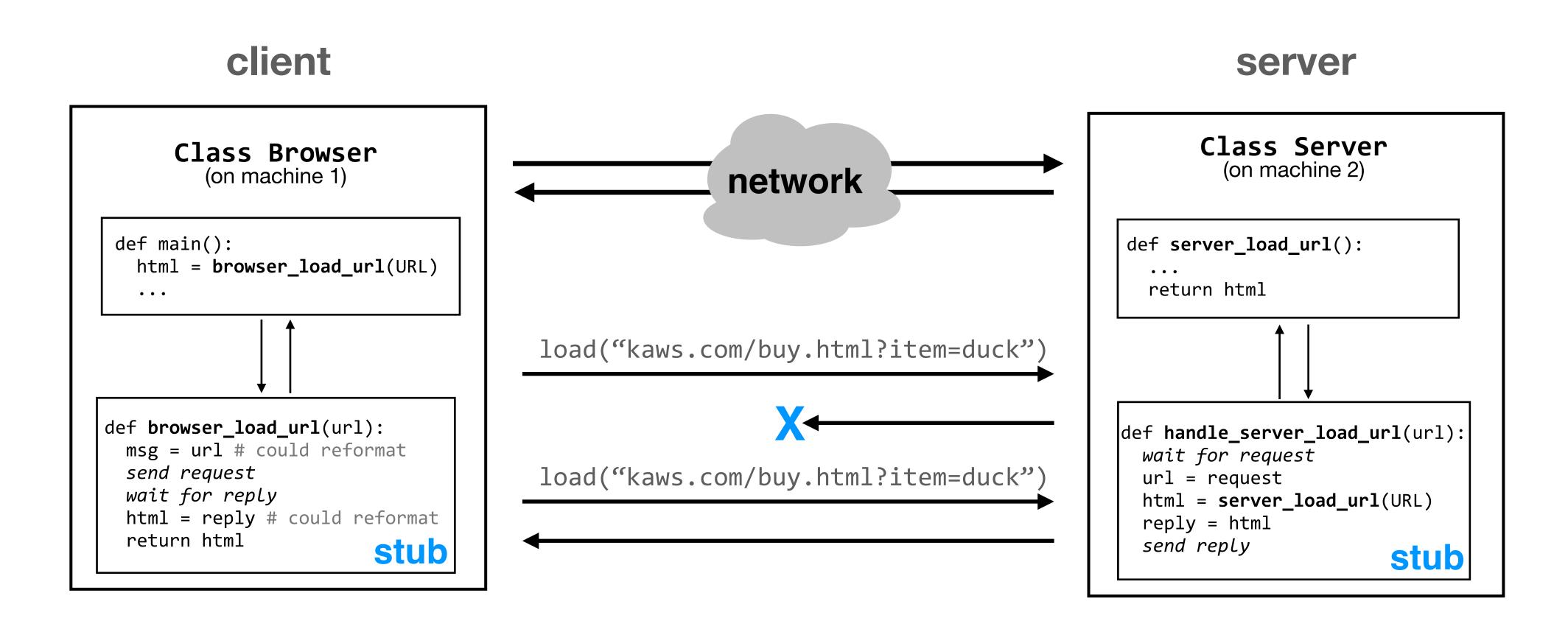
On the other hand, YouTube TV viewers needed to be very careful about monitoring their social

accounts during the game. The vMVPD consistently delivered almost a full down behind the action on the OTA broadcast. When the Chiefs went into hurry-up offense in the fourth quarter, the YouTube TV stream was almost two downs behind at one point!

last time: enforced modularity via client/server + naming



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today: what if we don't want to put each module on a separate machine?

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in order to enforce modularity + have an effective operating system, a few things need to happen

programs shouldn't be able to refer to virtualize memory (and corrupt) each others' memory

2. programs should be able to assume they don't need to communicate with each other

3. programs should be able to **share a CPU** without one program halting the progress of the others

assume one program per CPU

(for today)

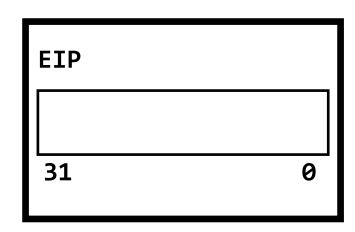
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CPU ₁	(used by program ₁)

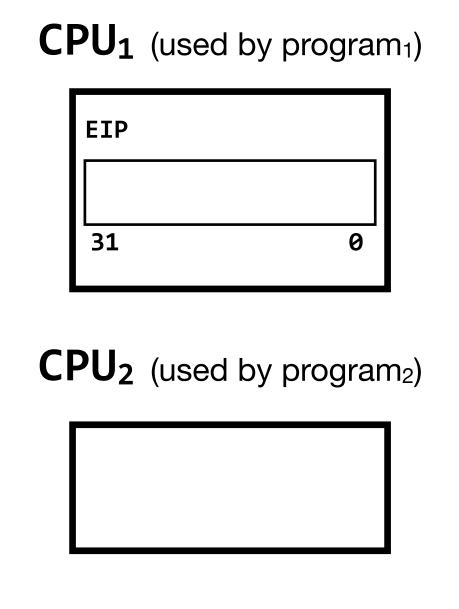
what we have: 2³² bytes of memory; every program can't *actually* have access to the full 32-bit space

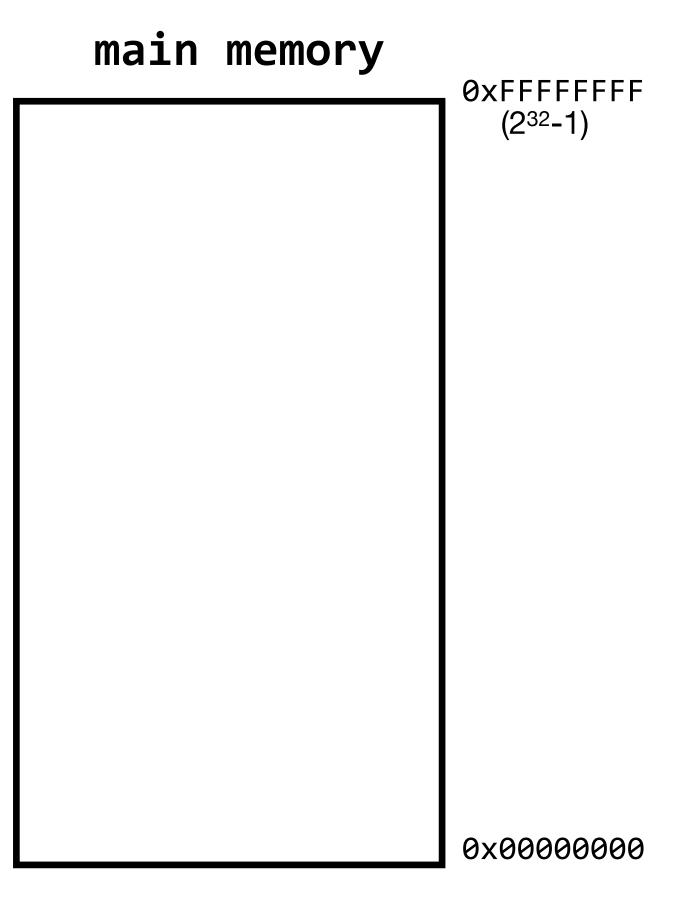
CPU₁ (used by program₁)



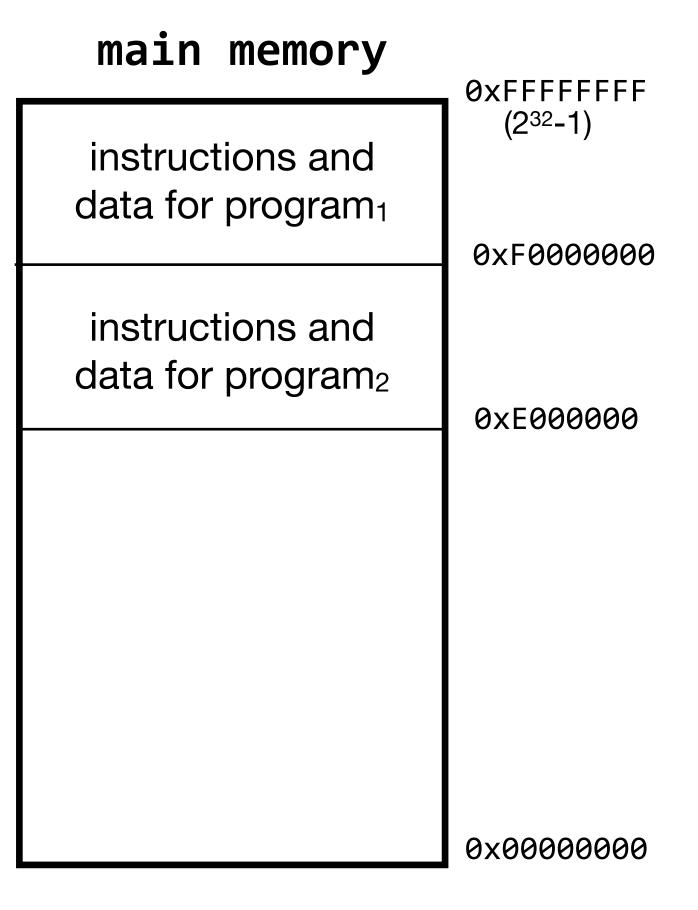
CPU₁ (used by program ₁)					
	EIP				
	31			0	
CI	PU ₂	(used	by p	orogra	am ₂)

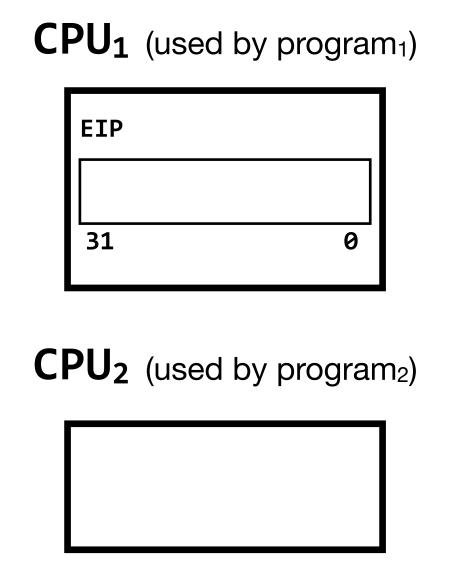
CPU ₁ (used by program ₁)	main memory
EIP	
CPU ₂ (used by program ₂)	

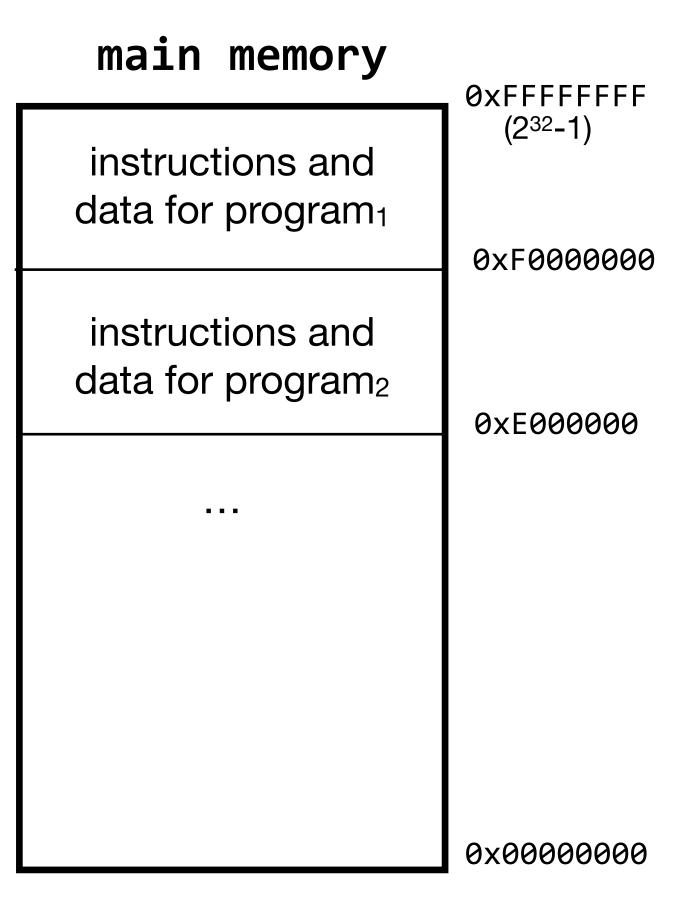




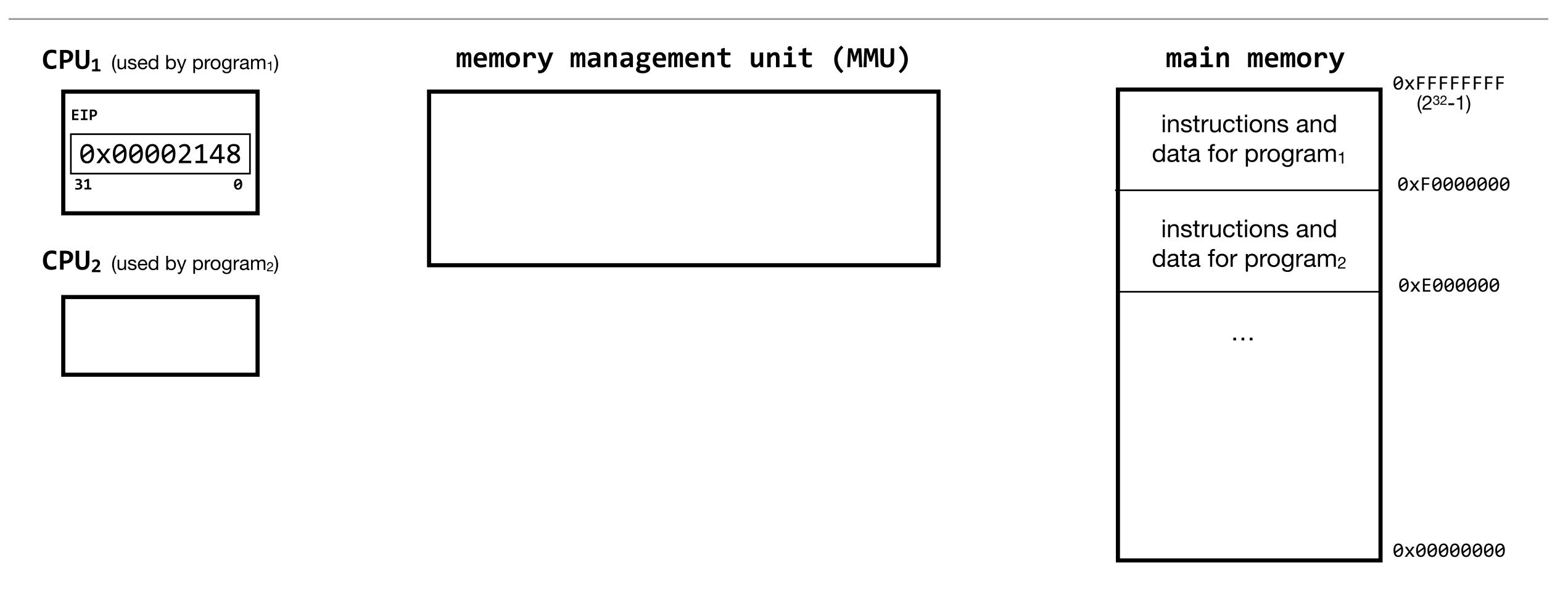
CI	PU ₁	(used	by	prog	gram ——	11)
	EIP					
	31				0	
	<u> </u>					
CI	PU ₂	(used	by	pro	gram	12)

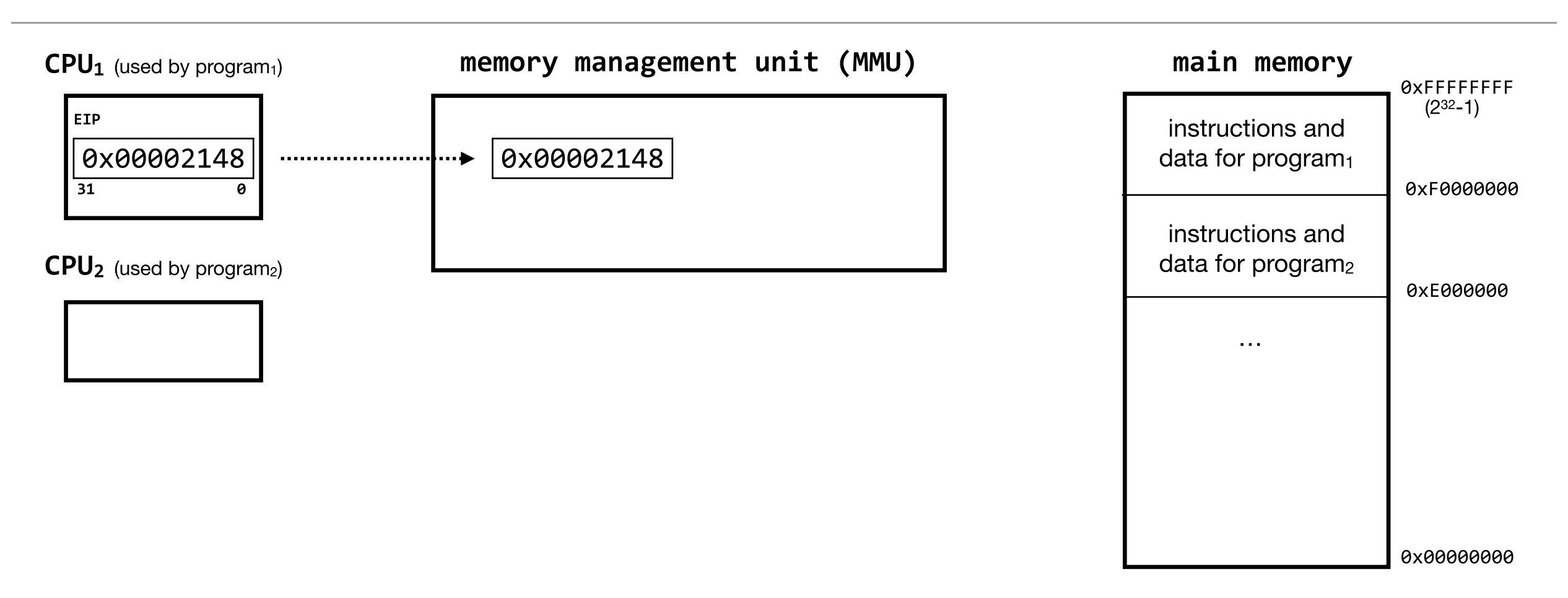


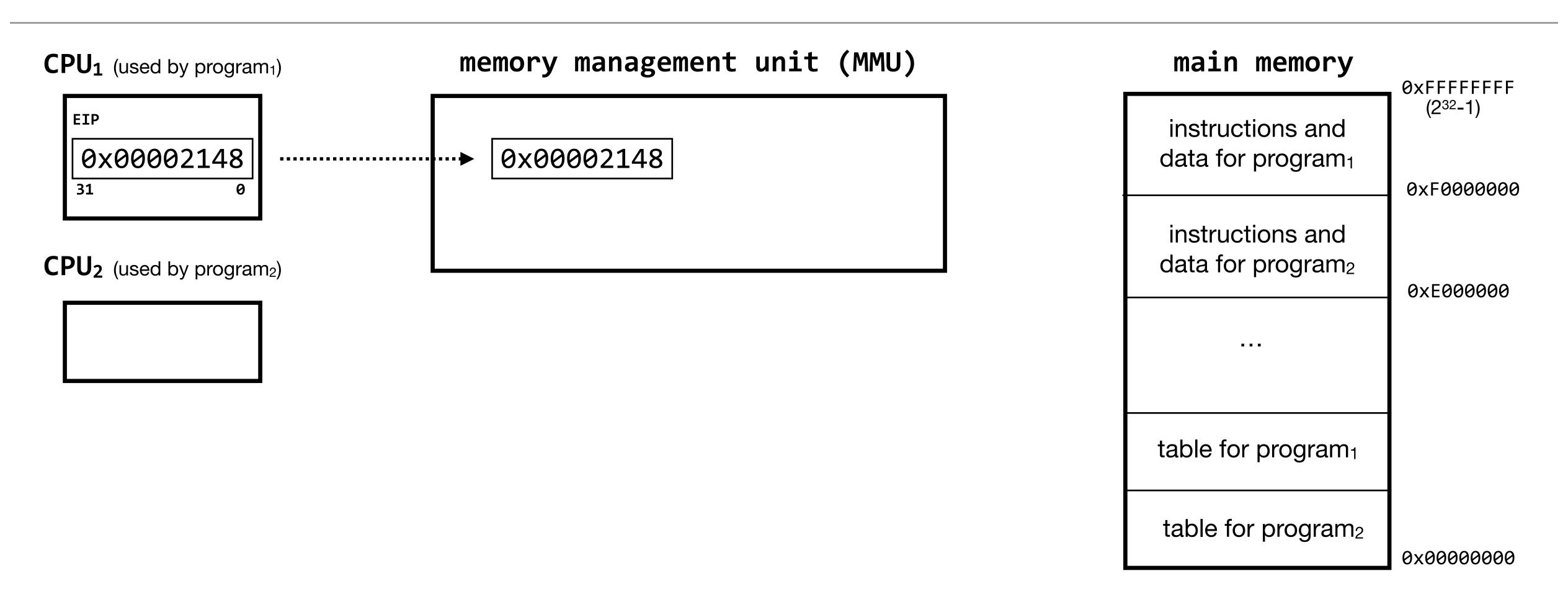


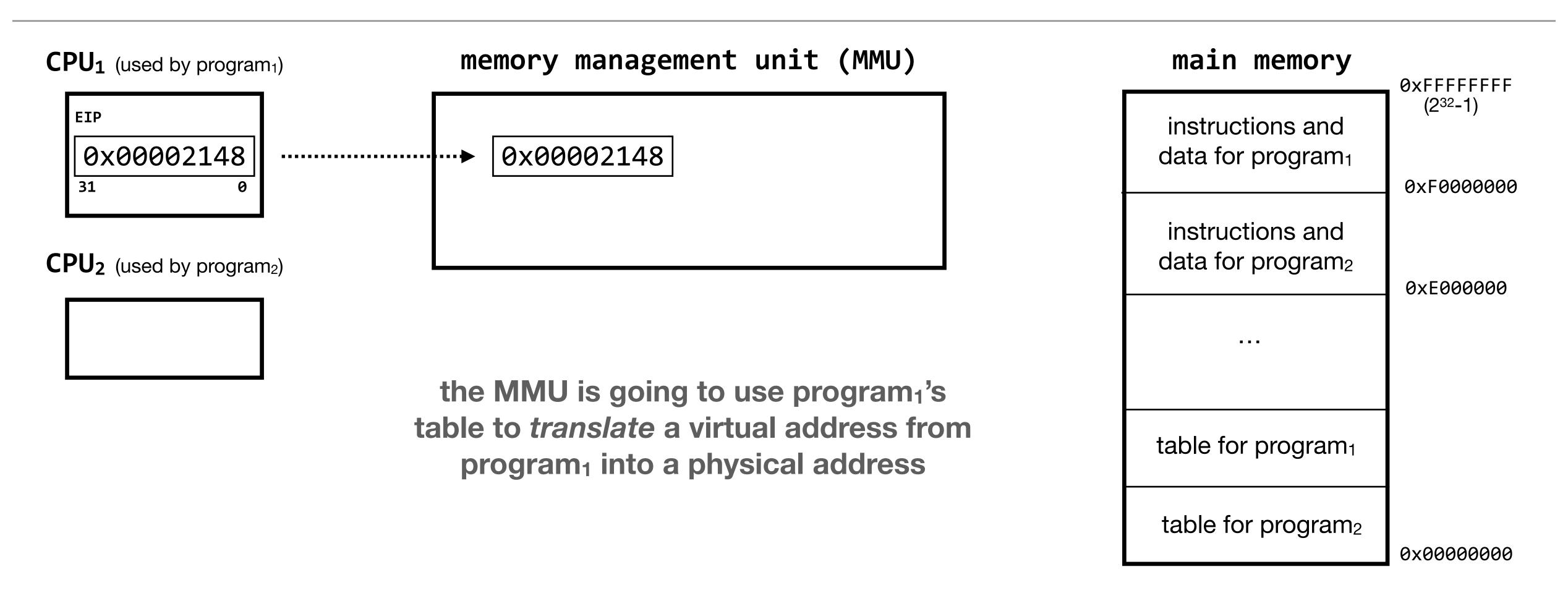


CPU ₁ (used by program ₁)	memory management unit (MMU)	main memory	_ 0xfffffff
EIP 31 0		instructions and data for program ₁	(2 ³² -1) 0xF0000000
CPU ₂ (used by program ₂)		instructions and data for program ₂	0xE000000
			0x00000000

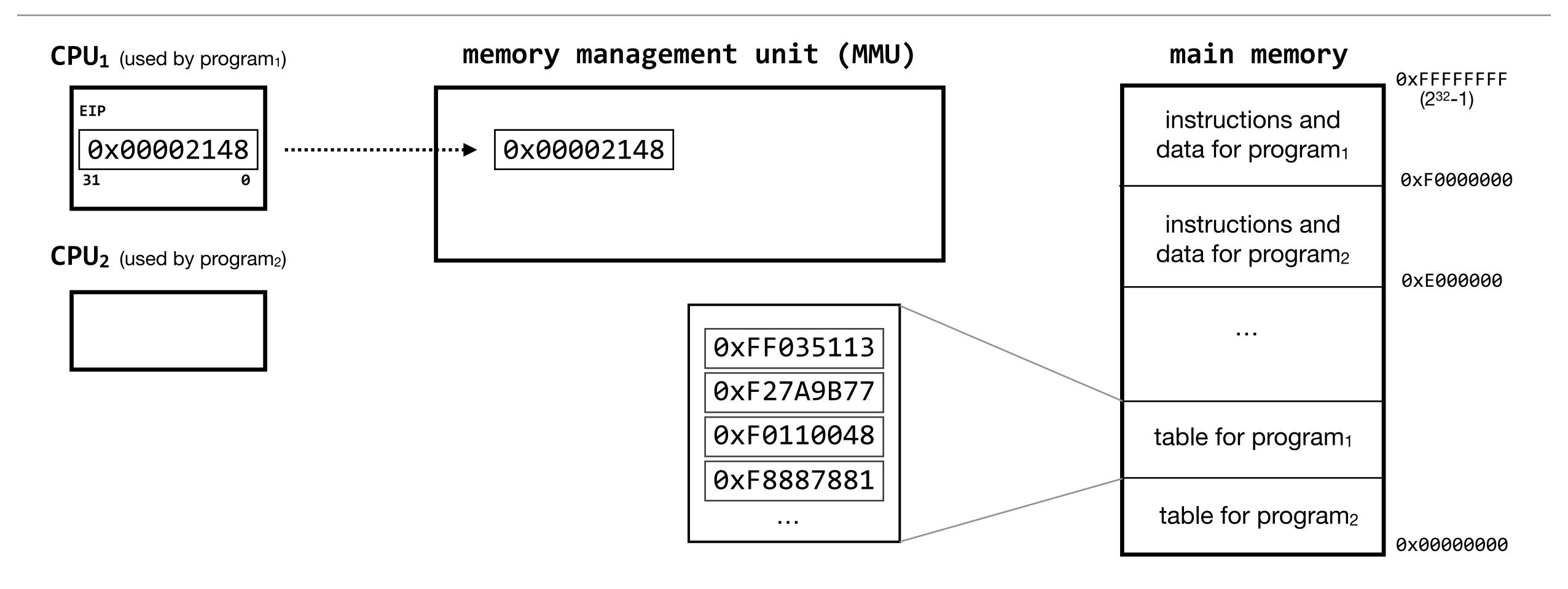






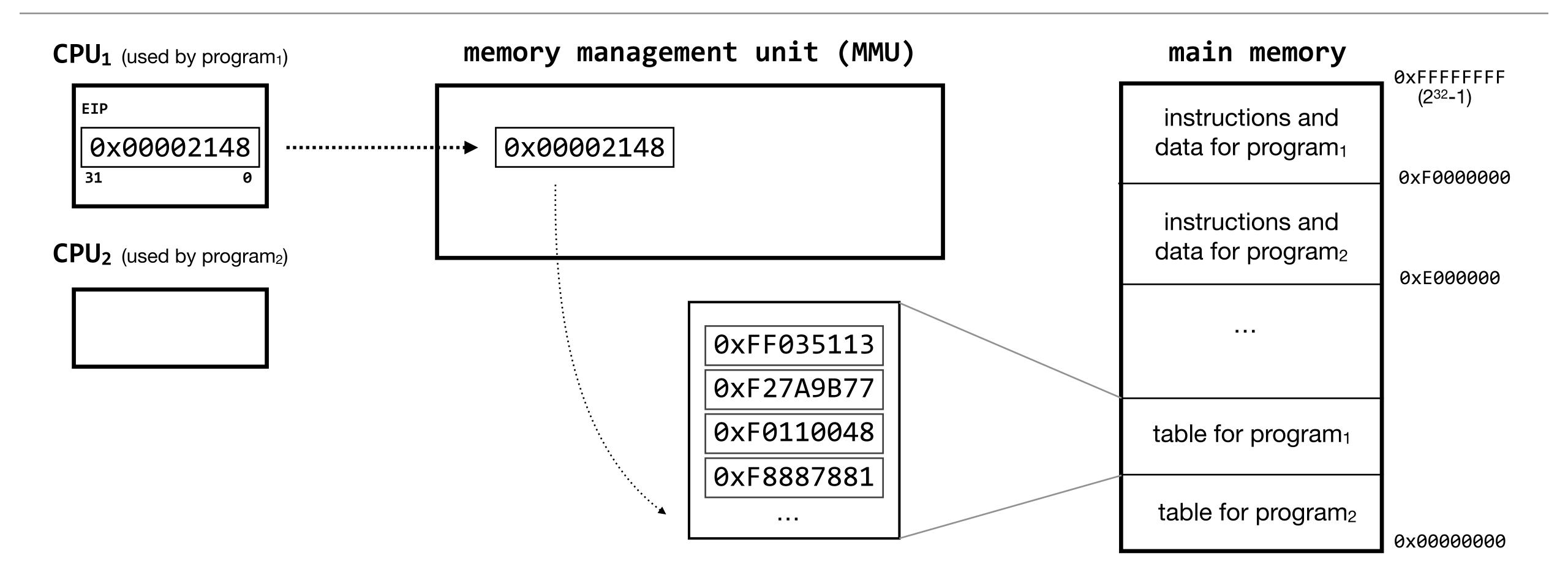


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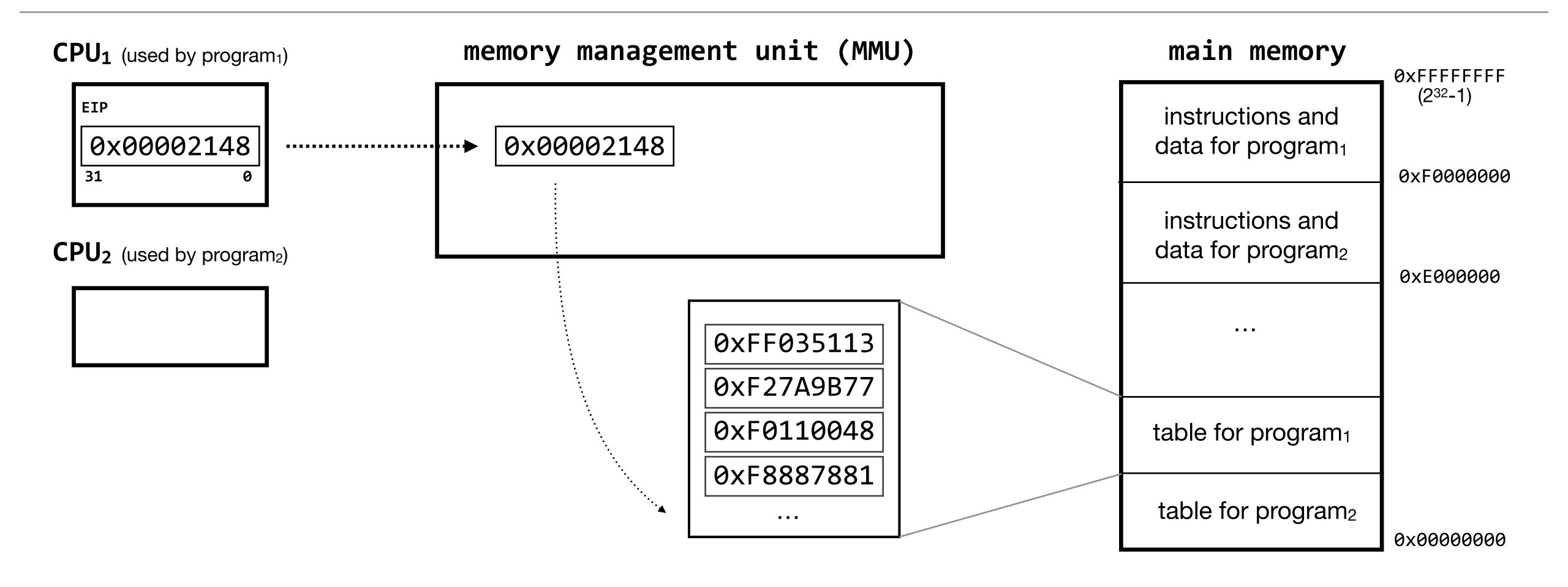
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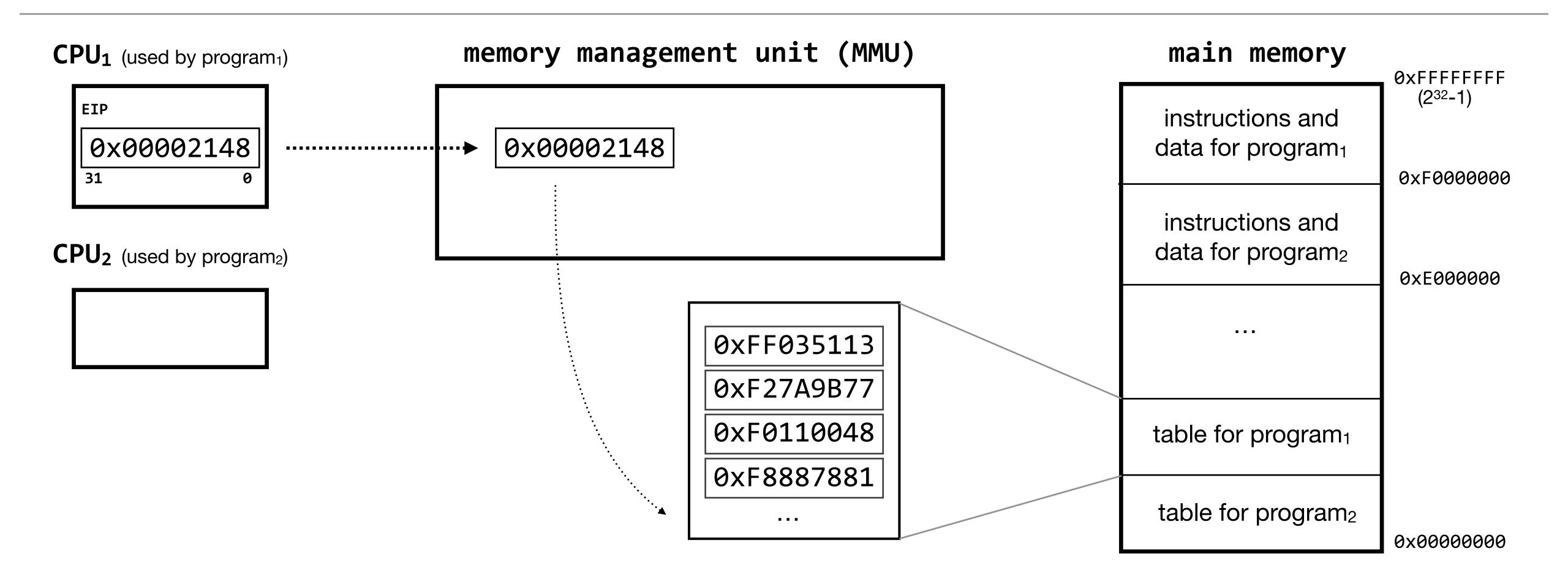
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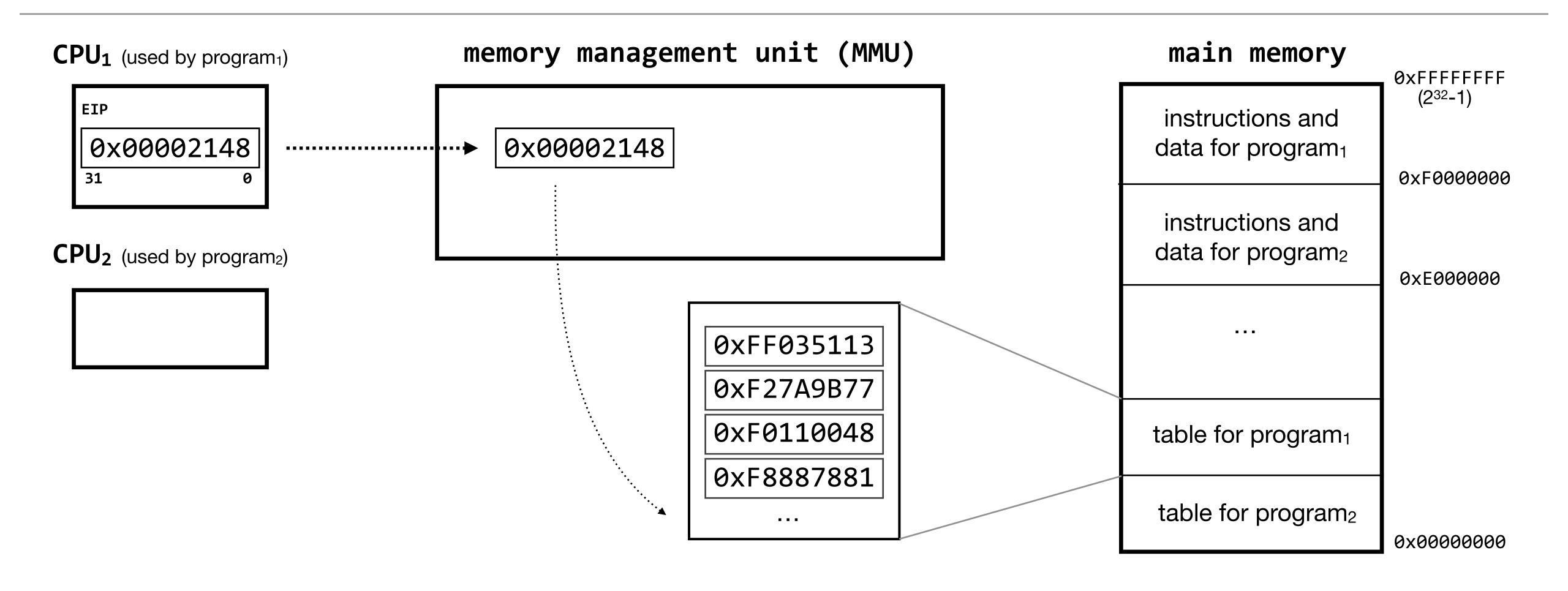
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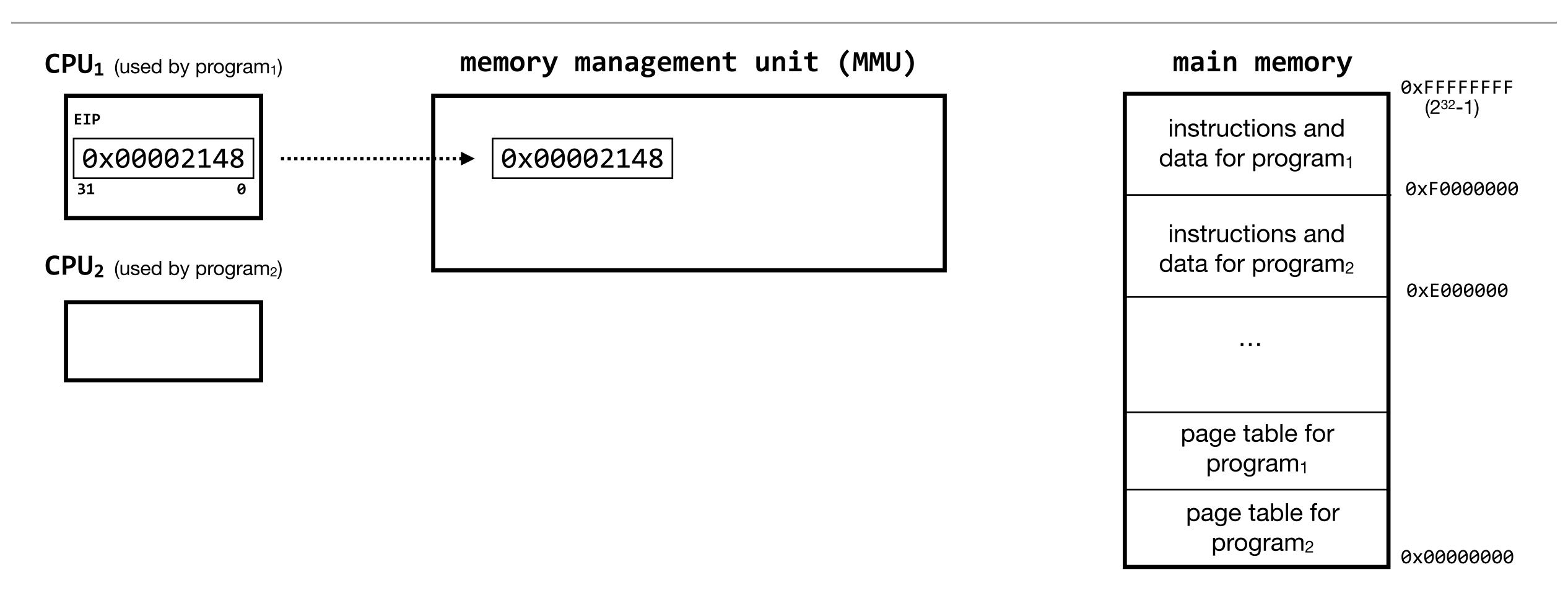
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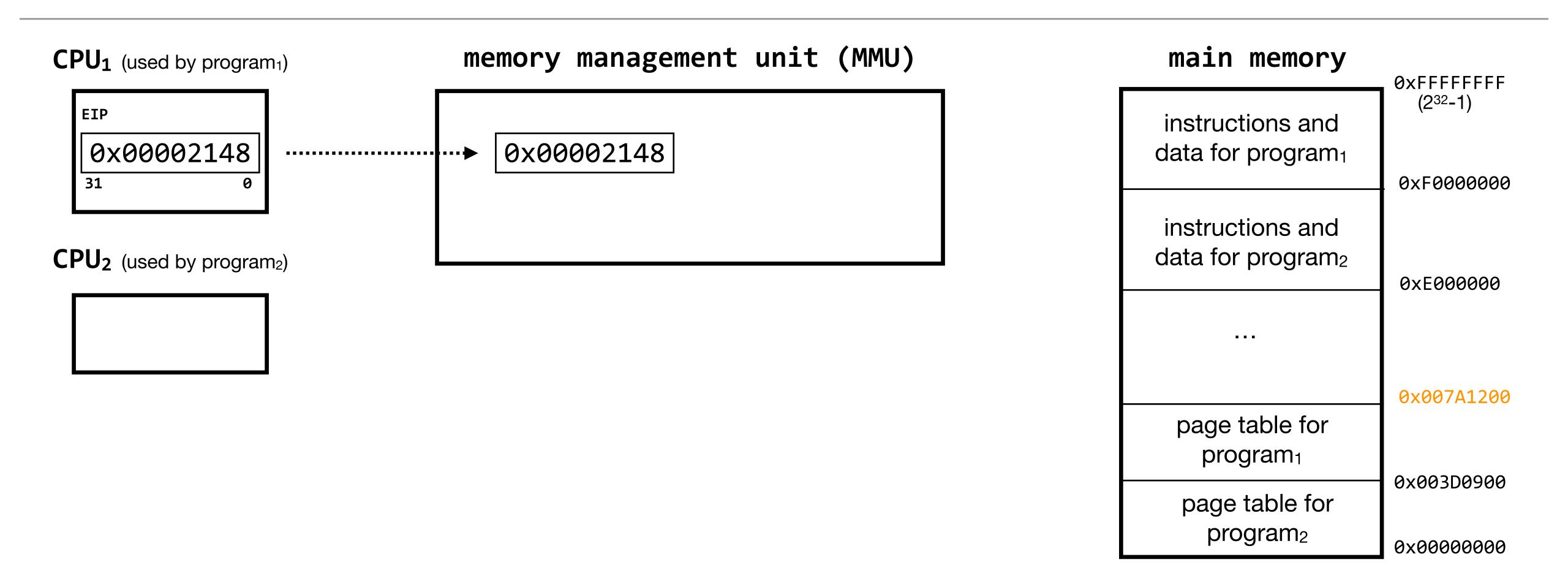


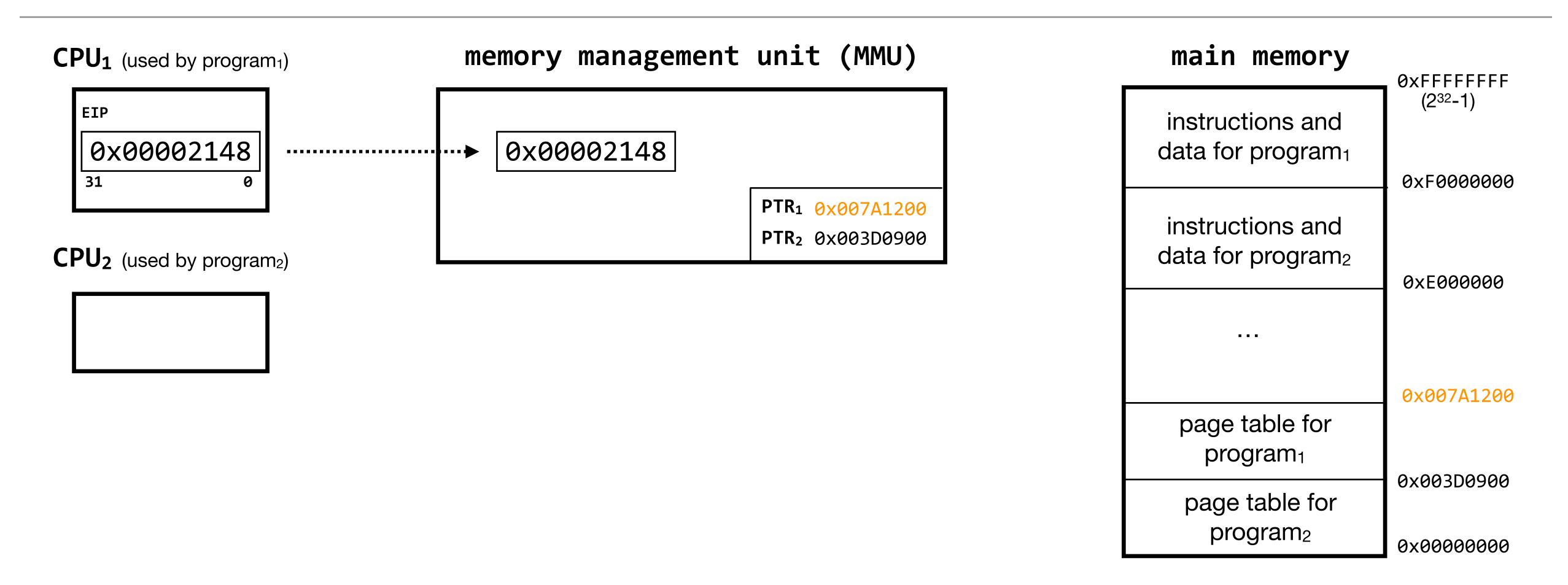
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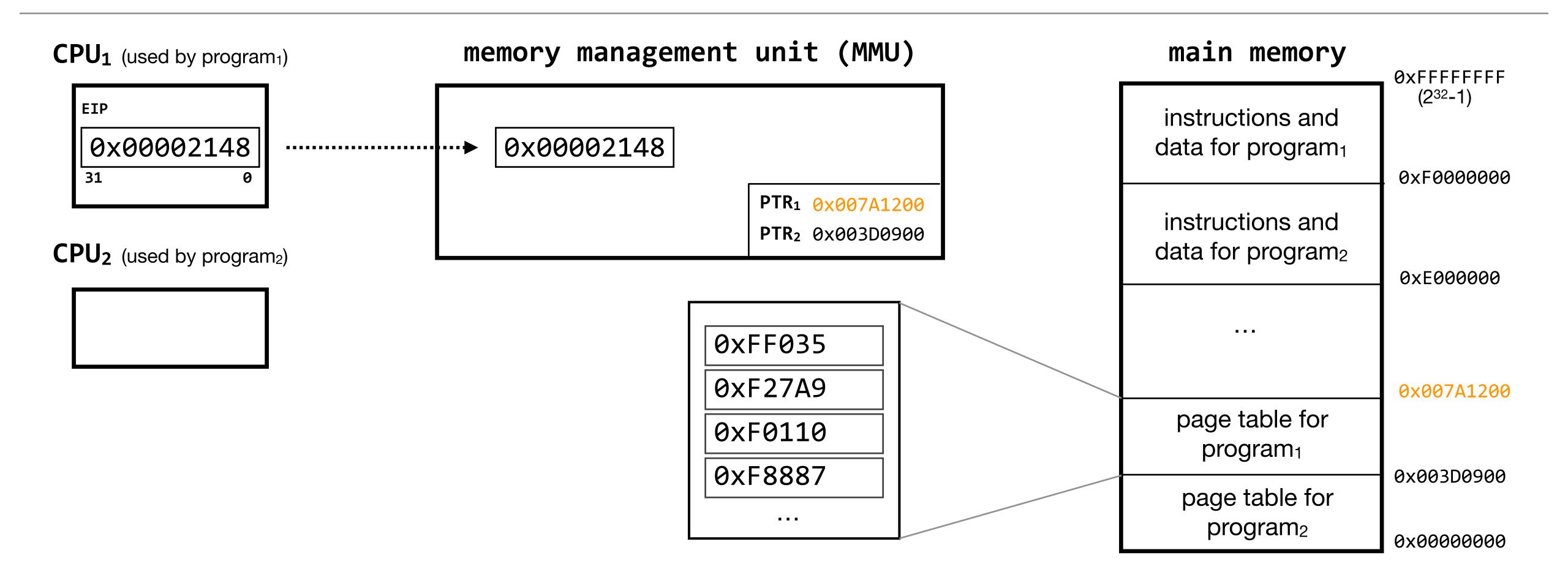
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16GB is *quite a lot* of memory

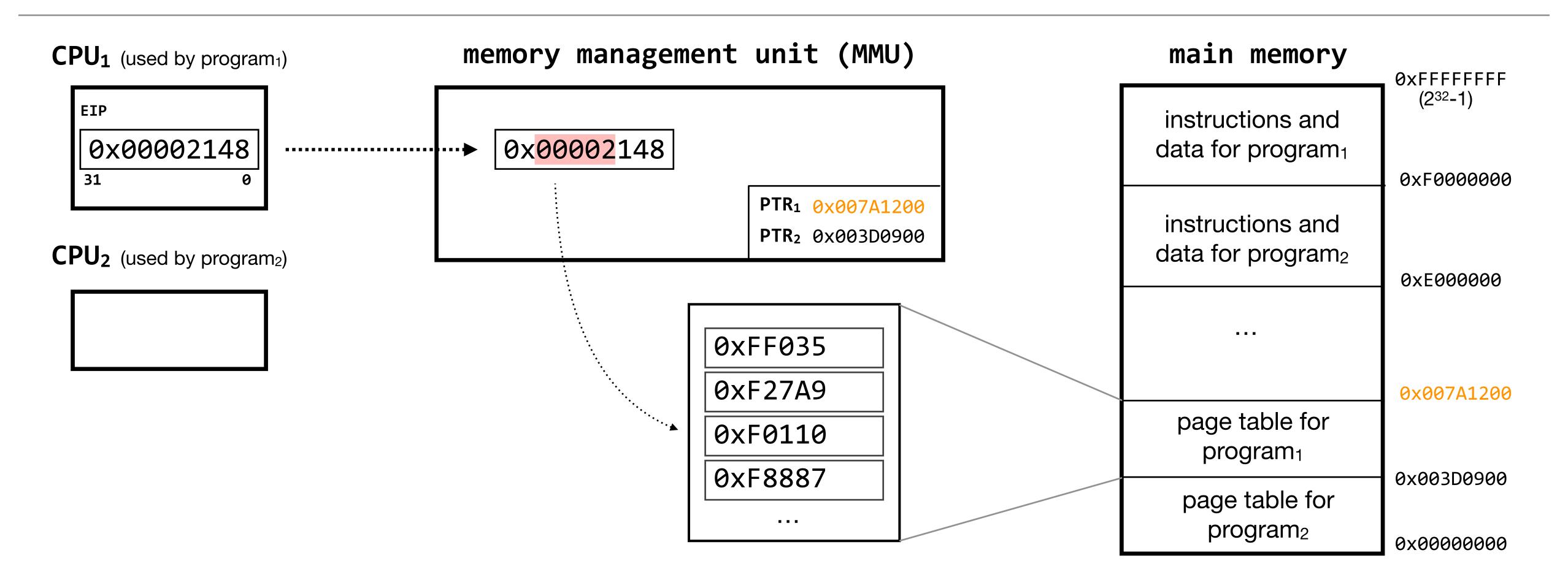








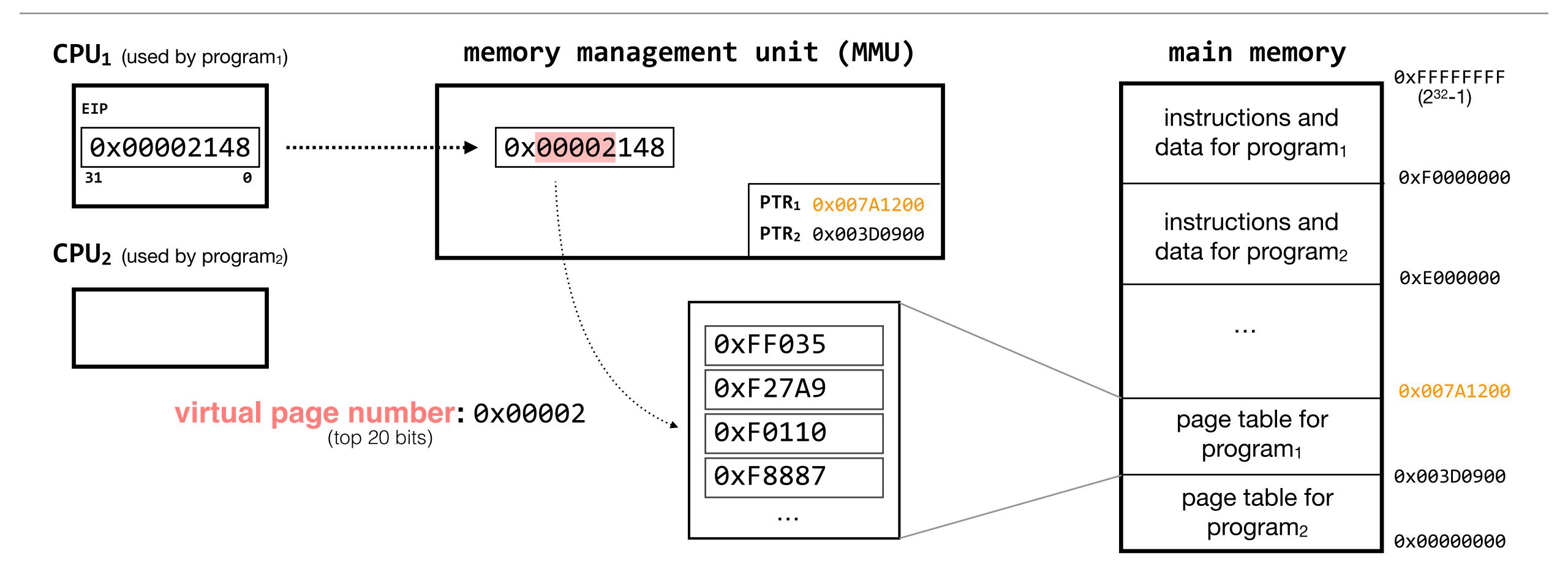
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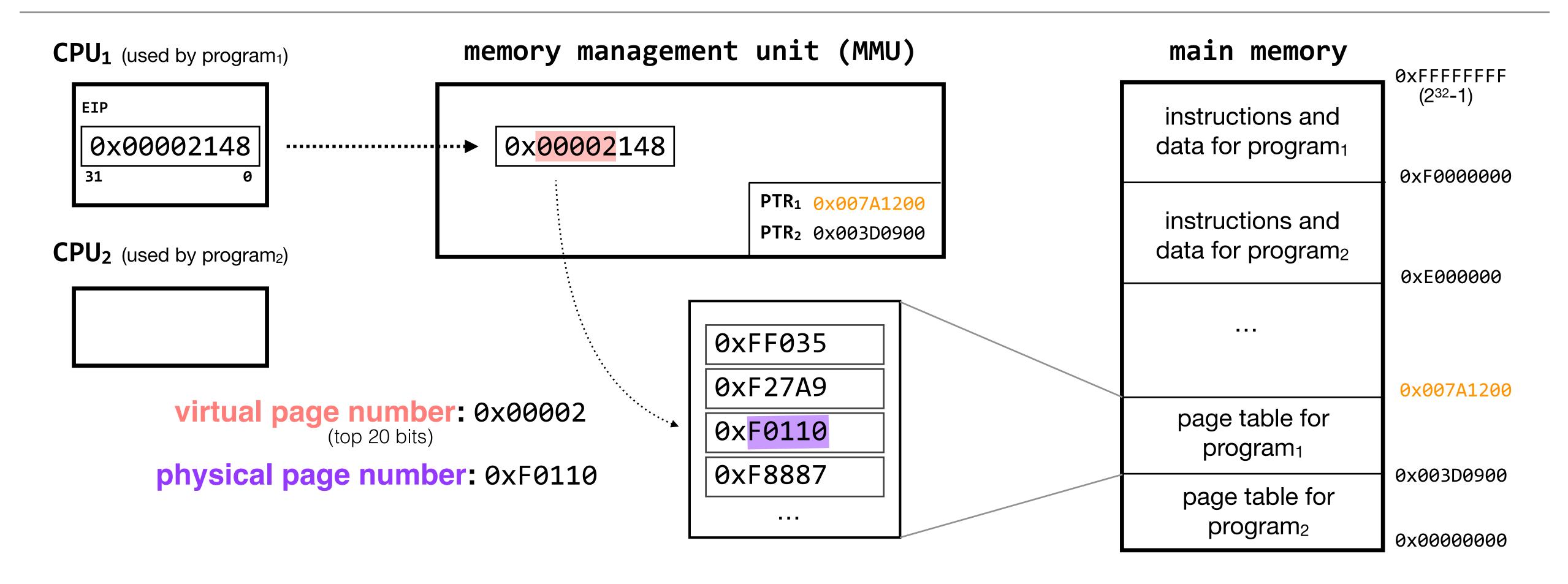
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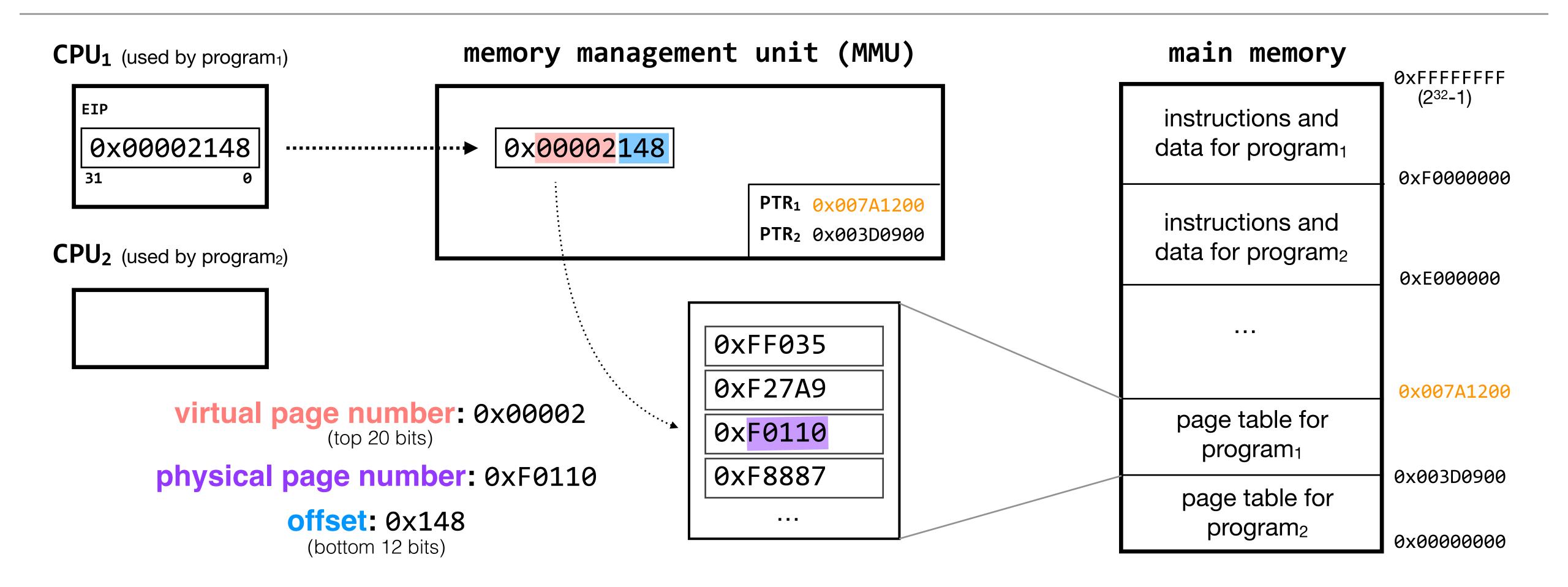
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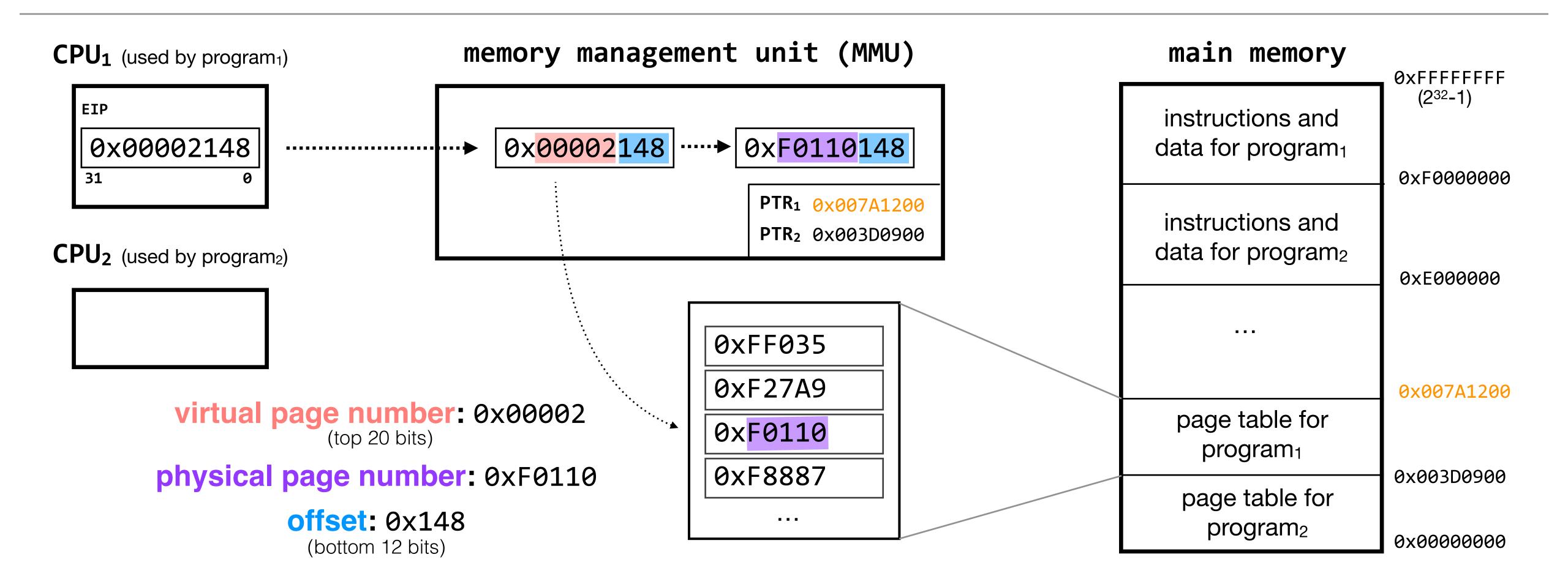
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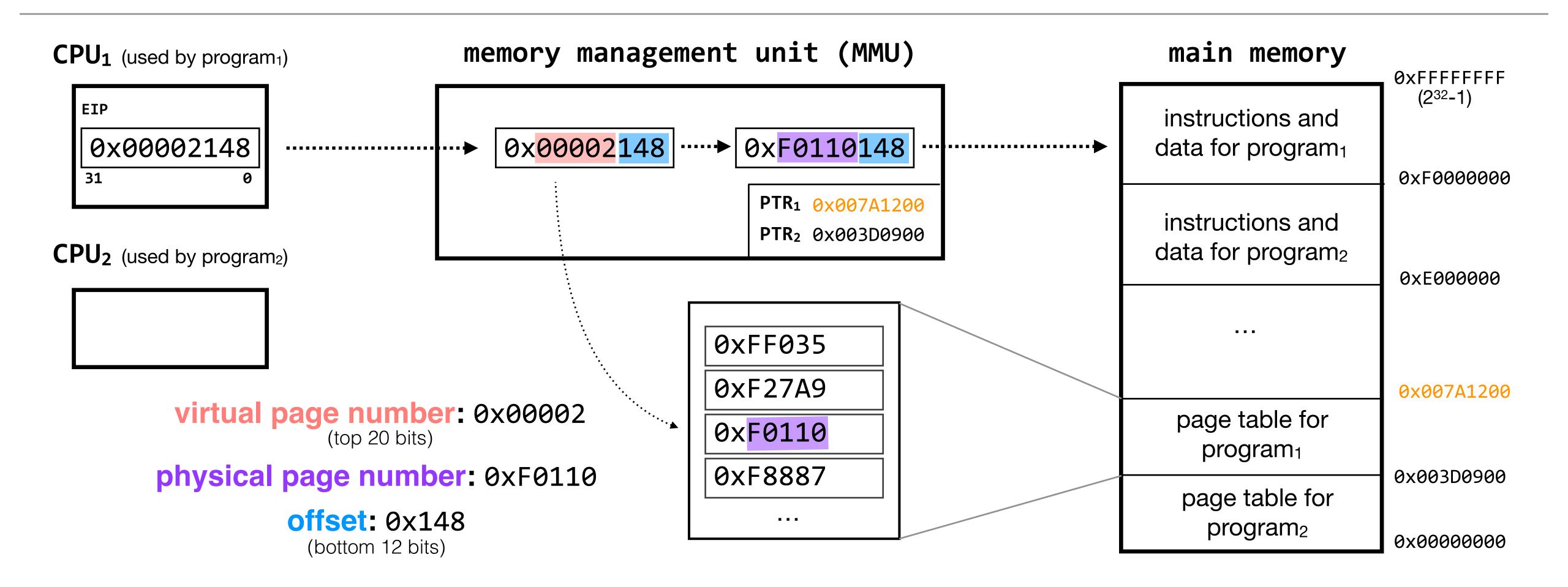
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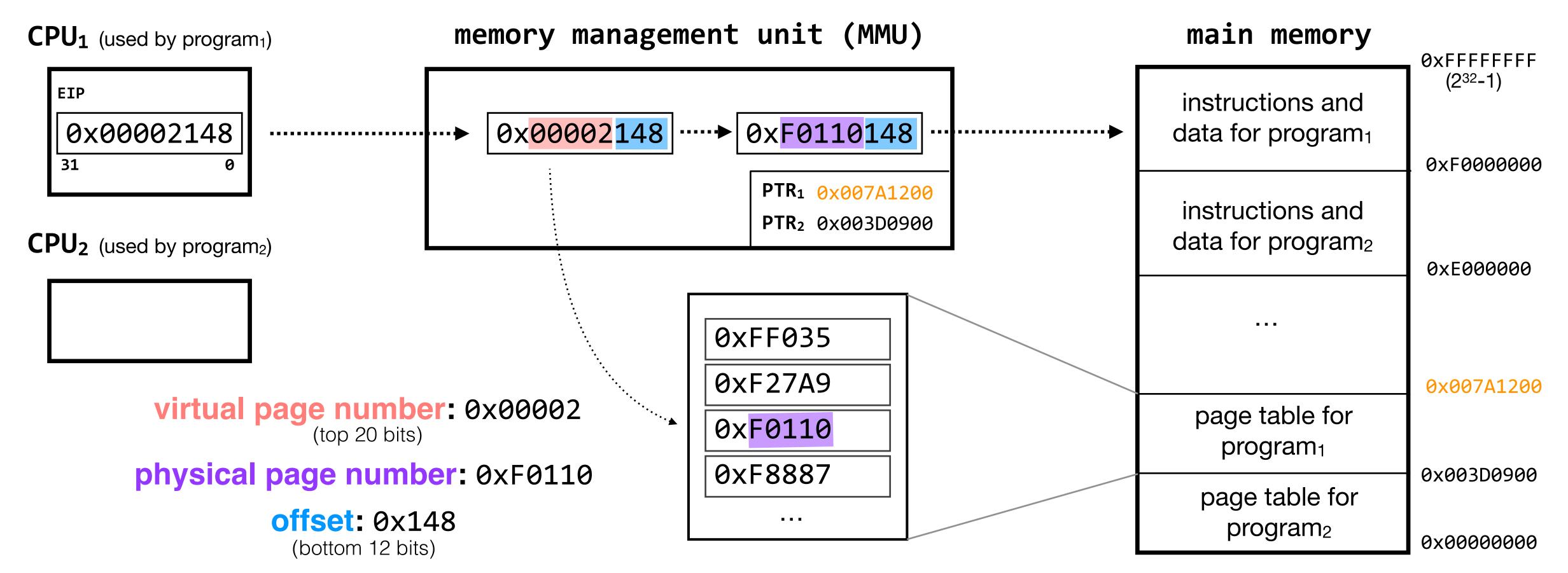
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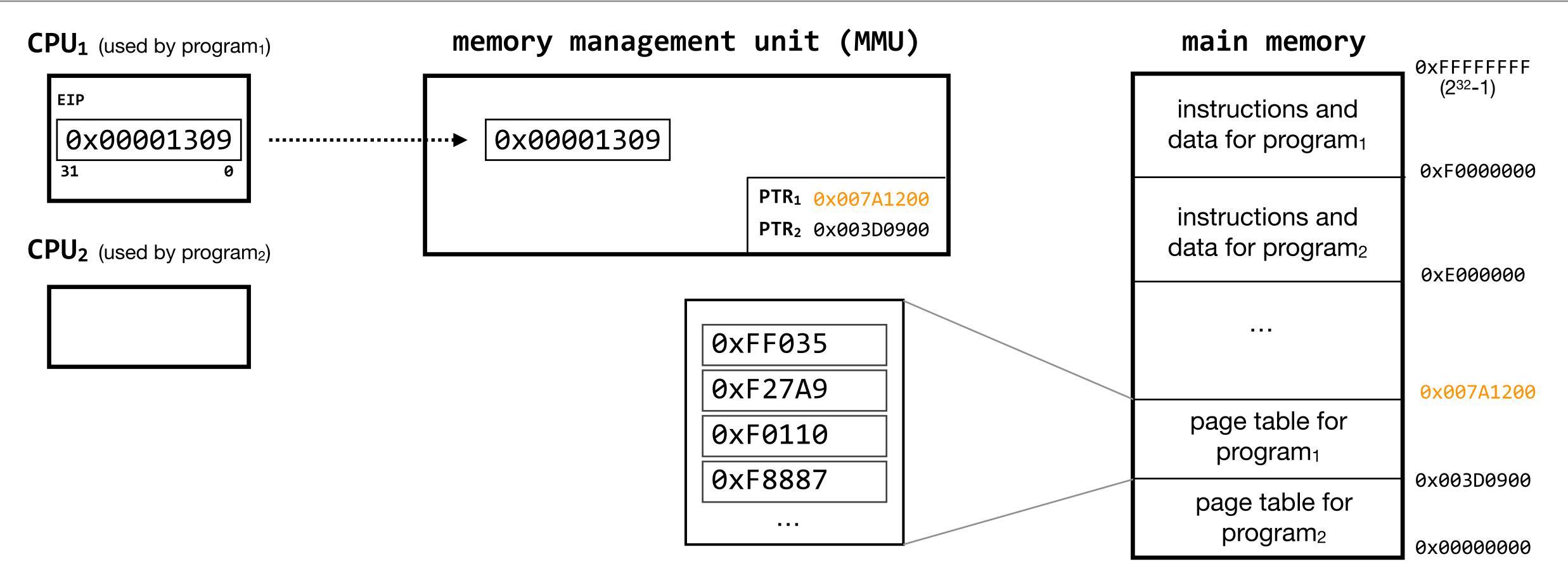


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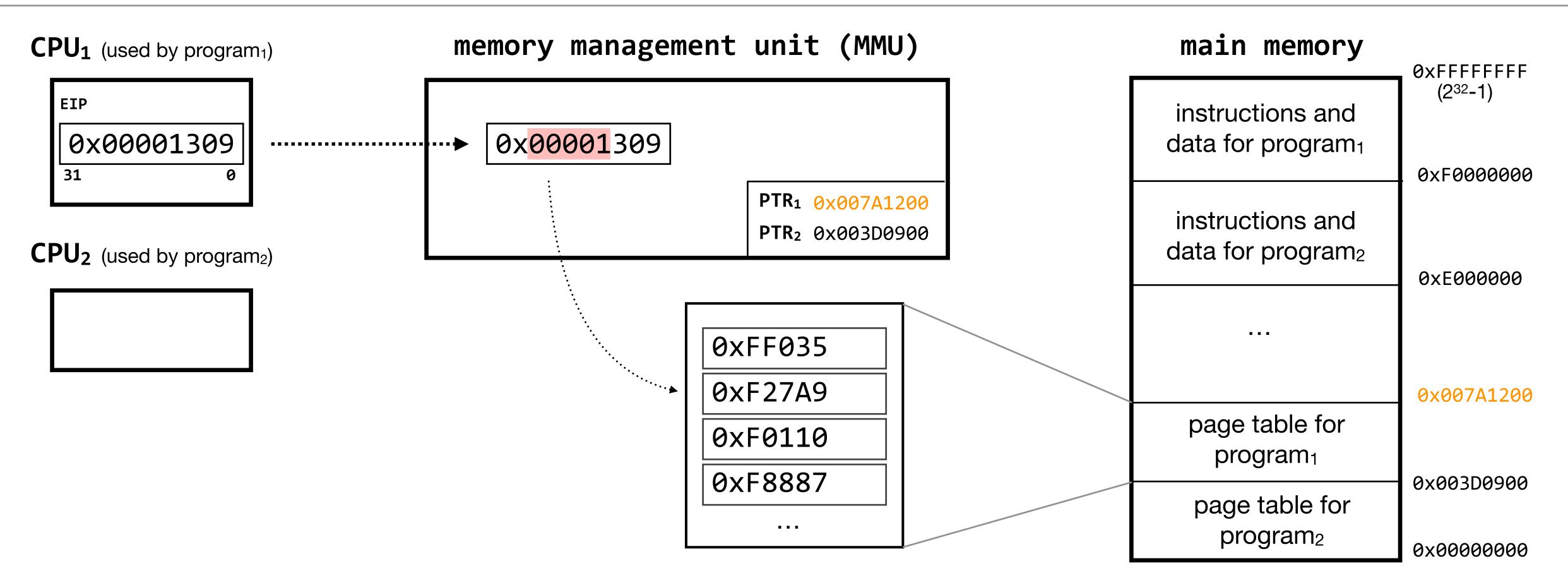


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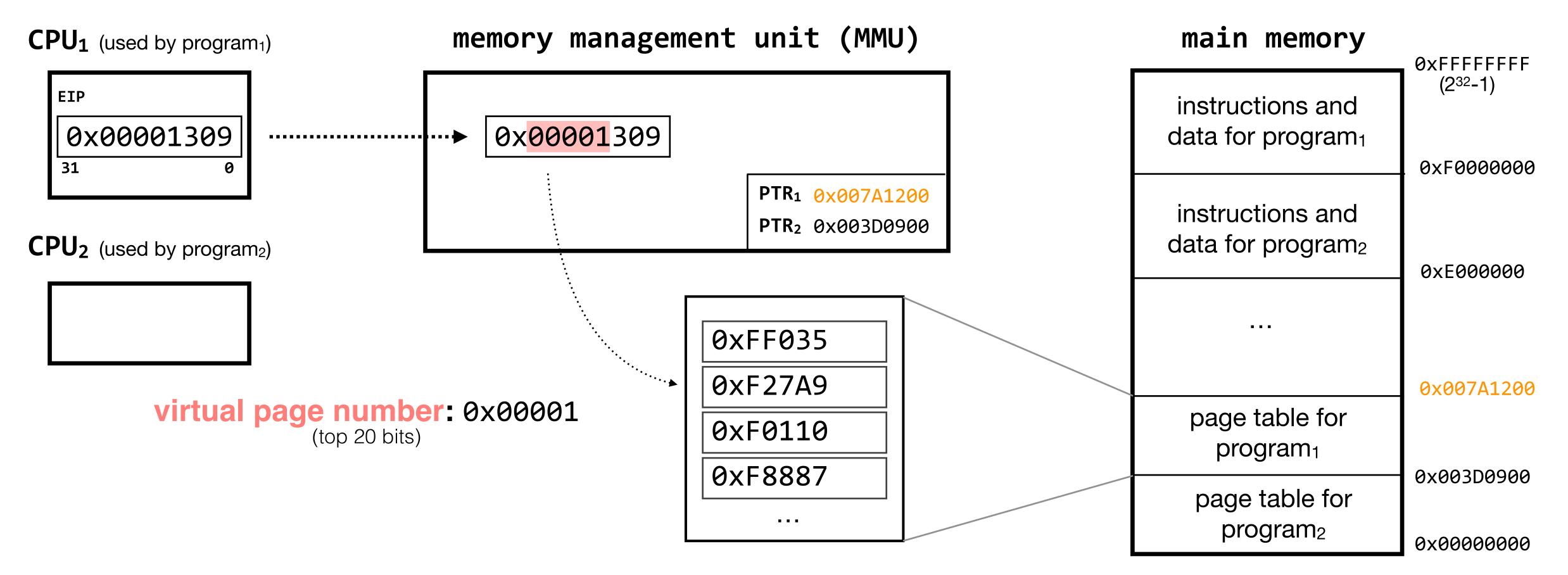


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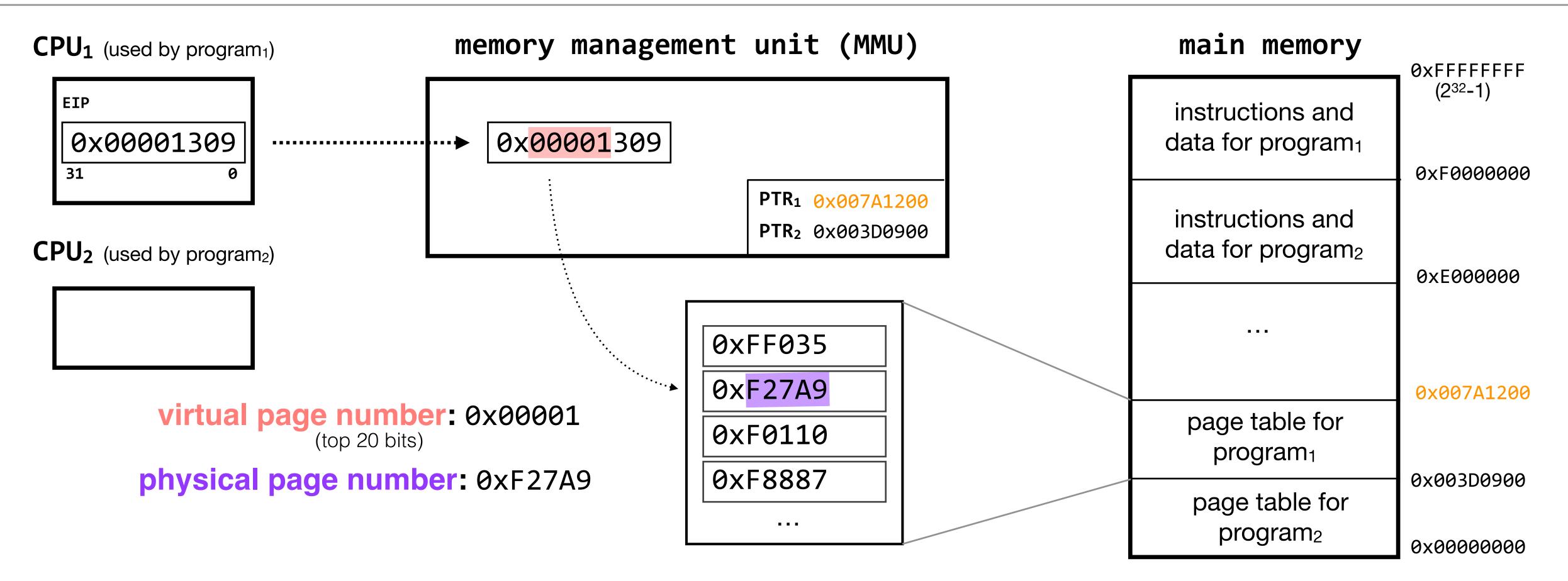


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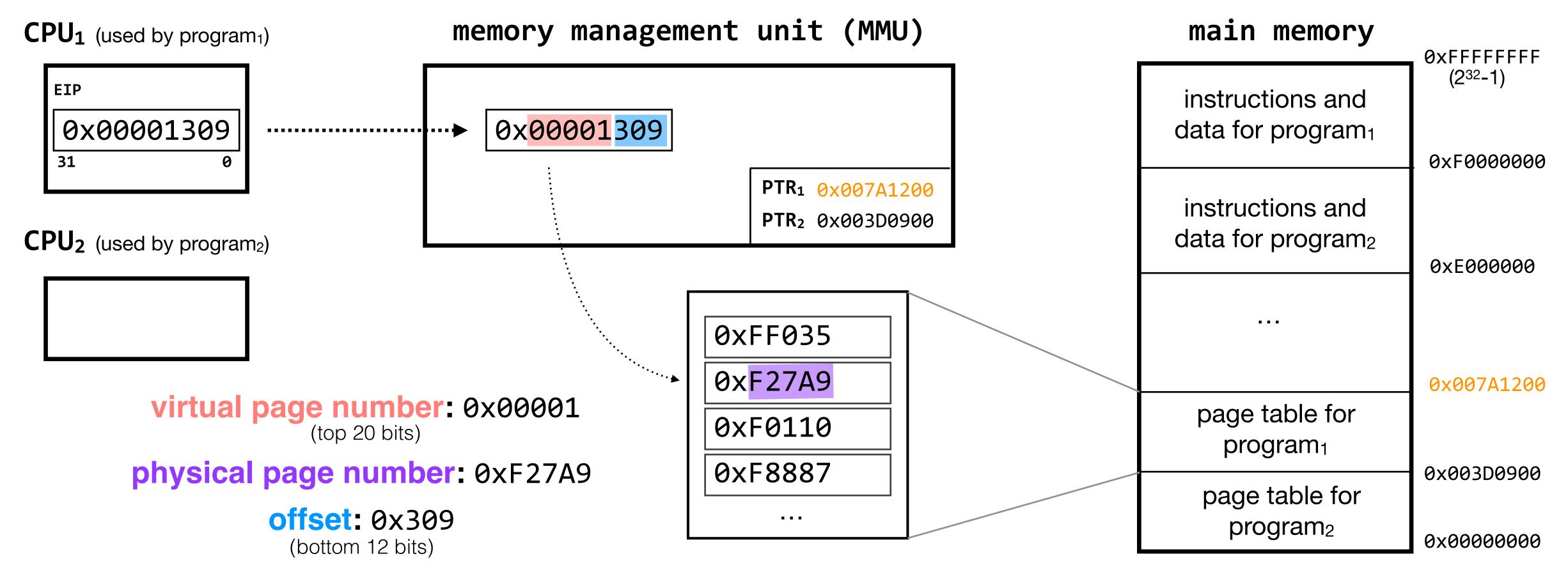


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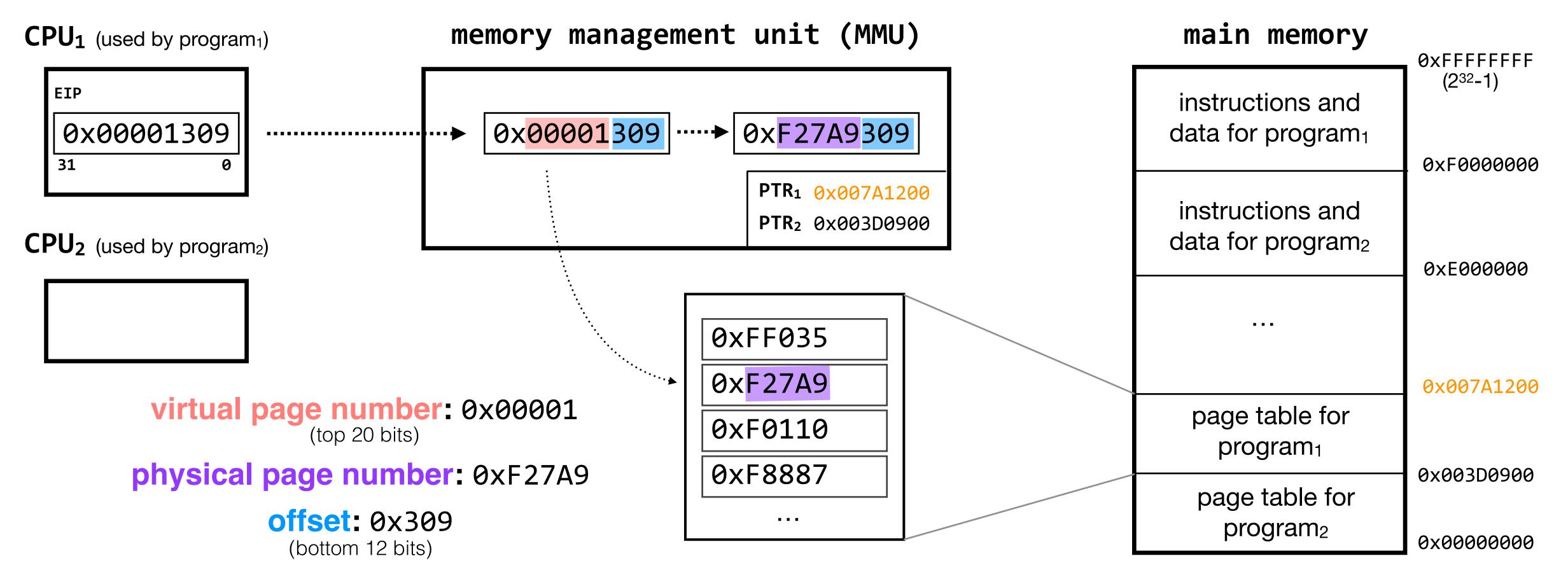


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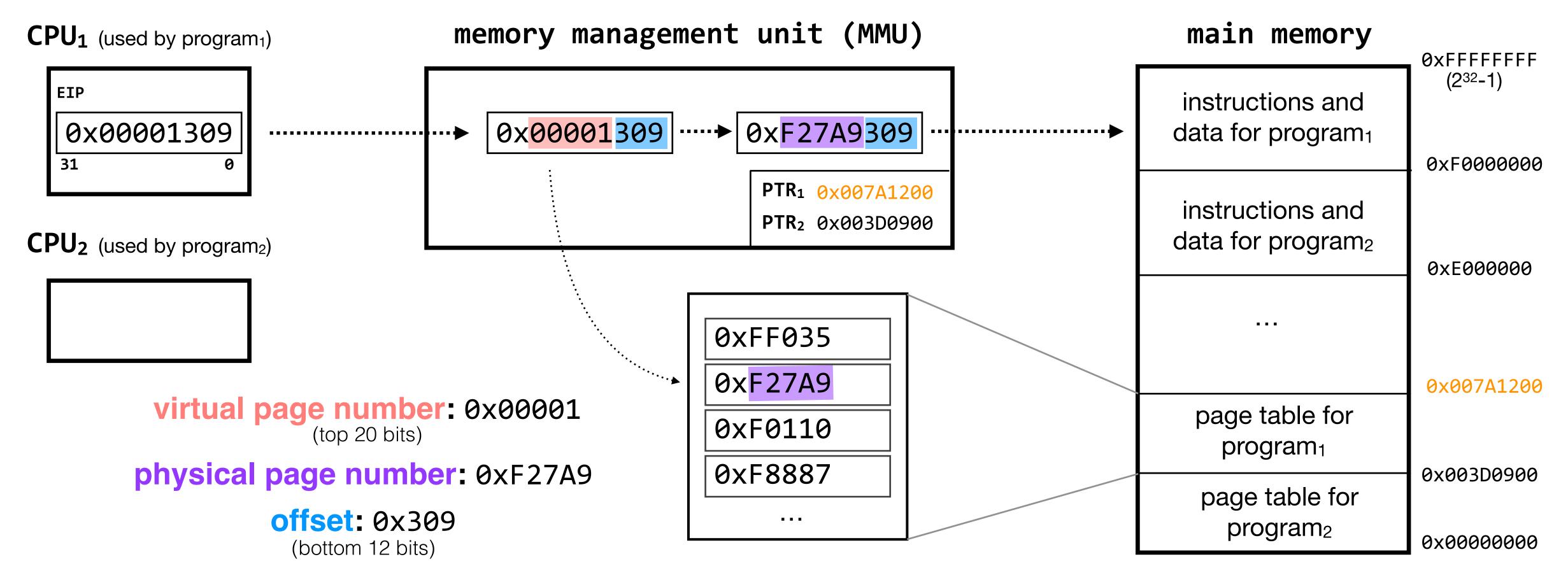


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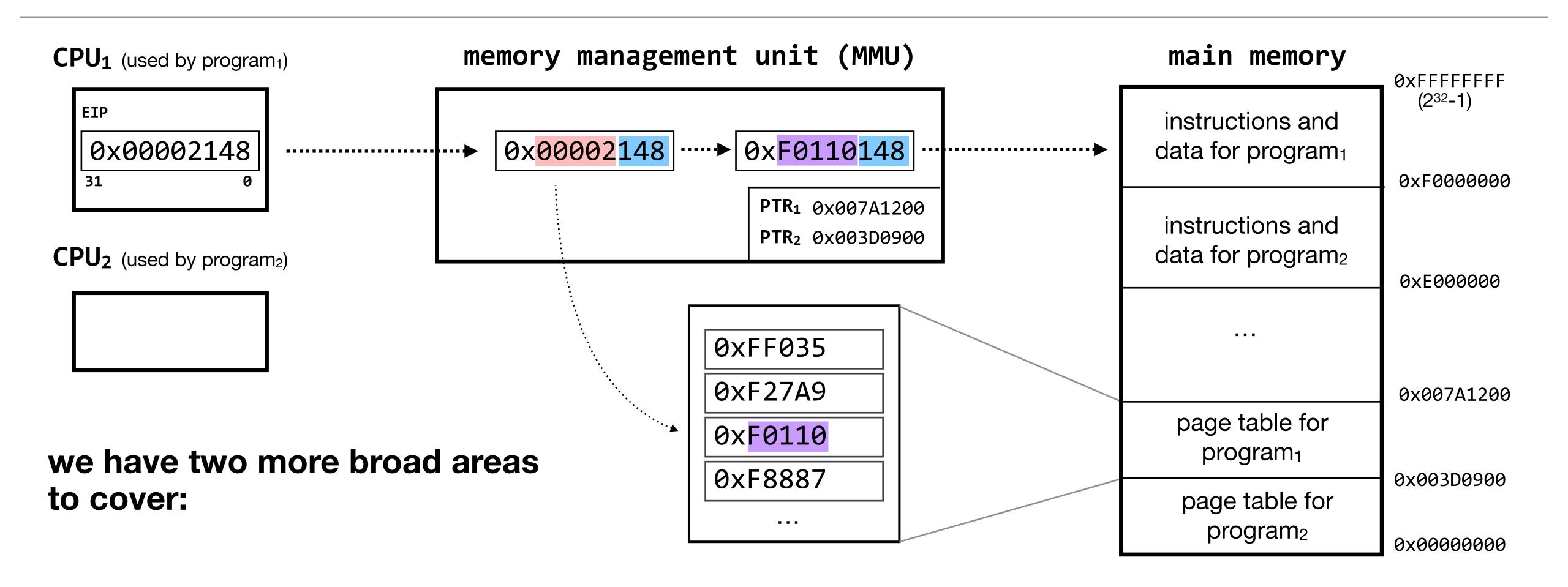
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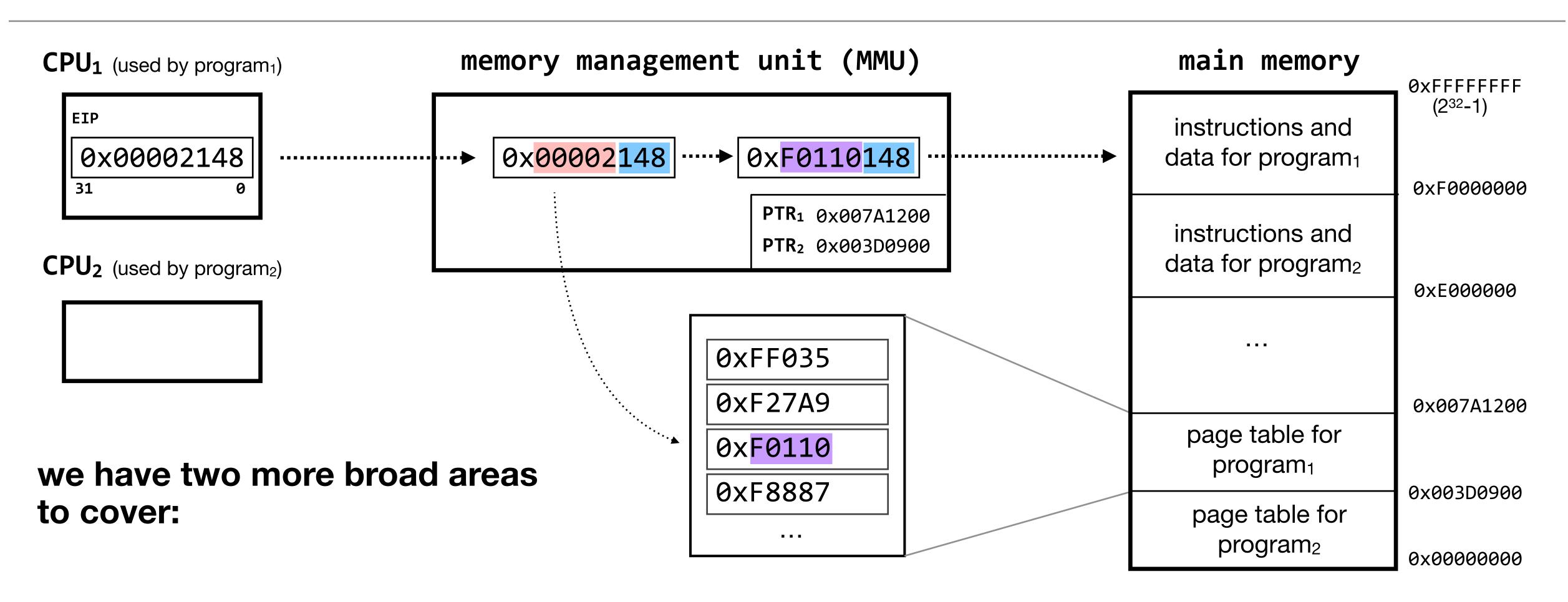


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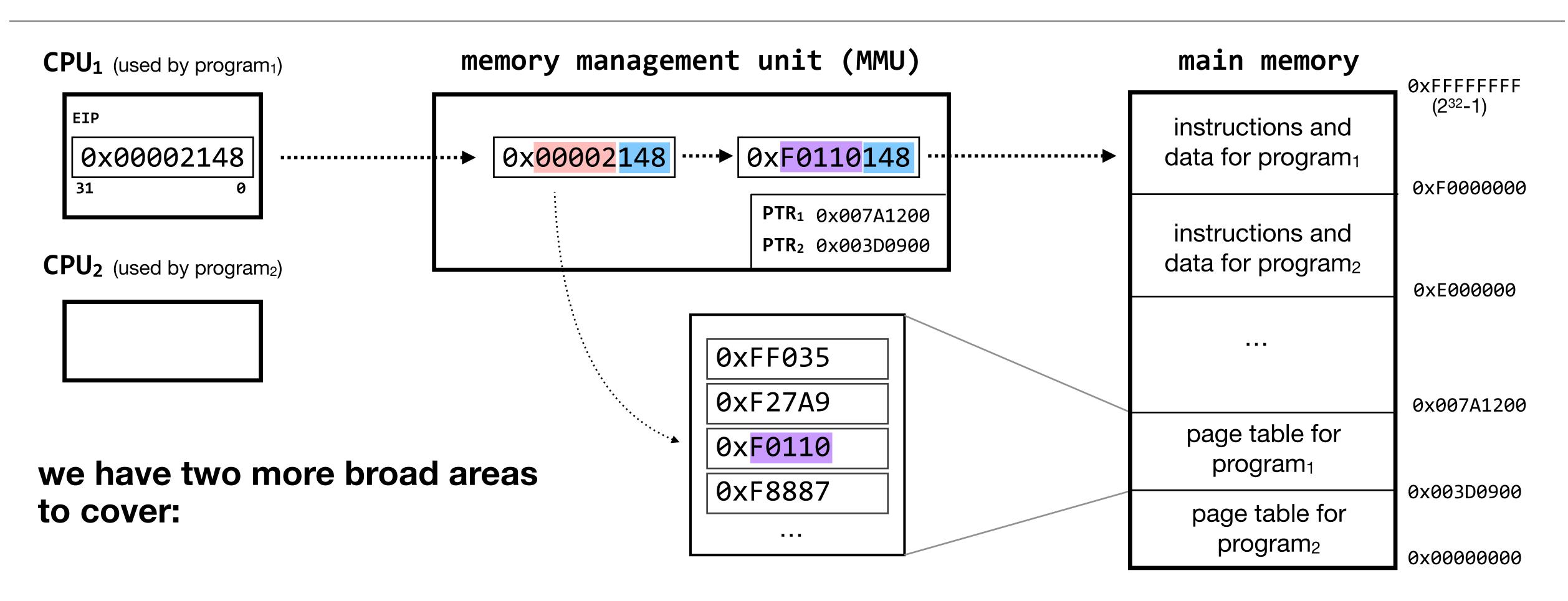
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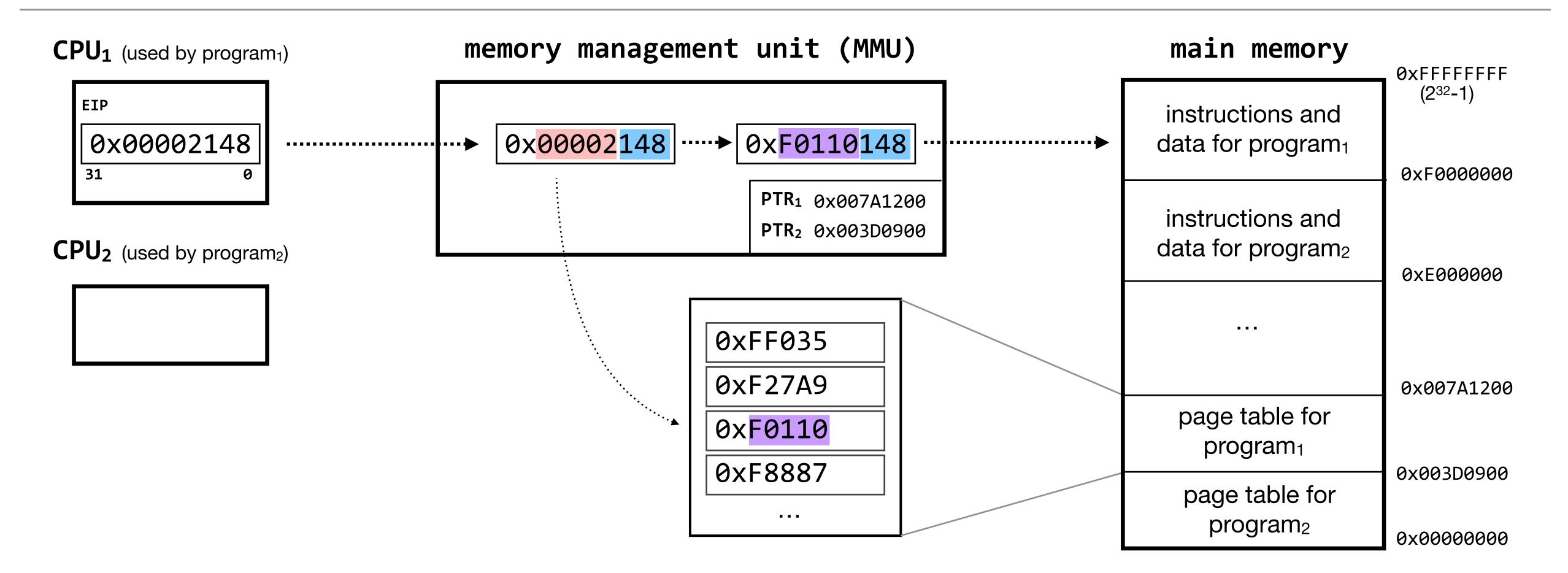


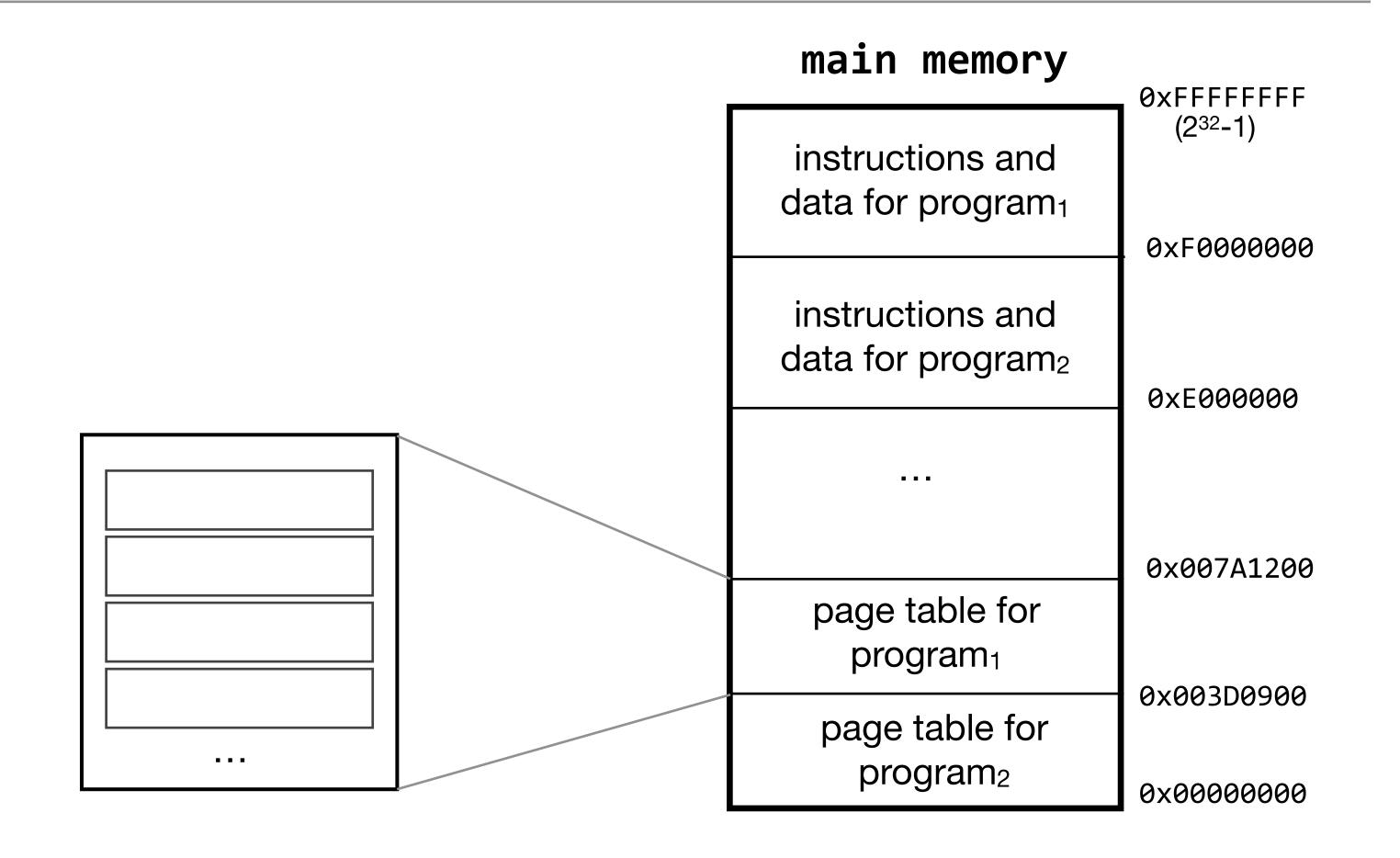
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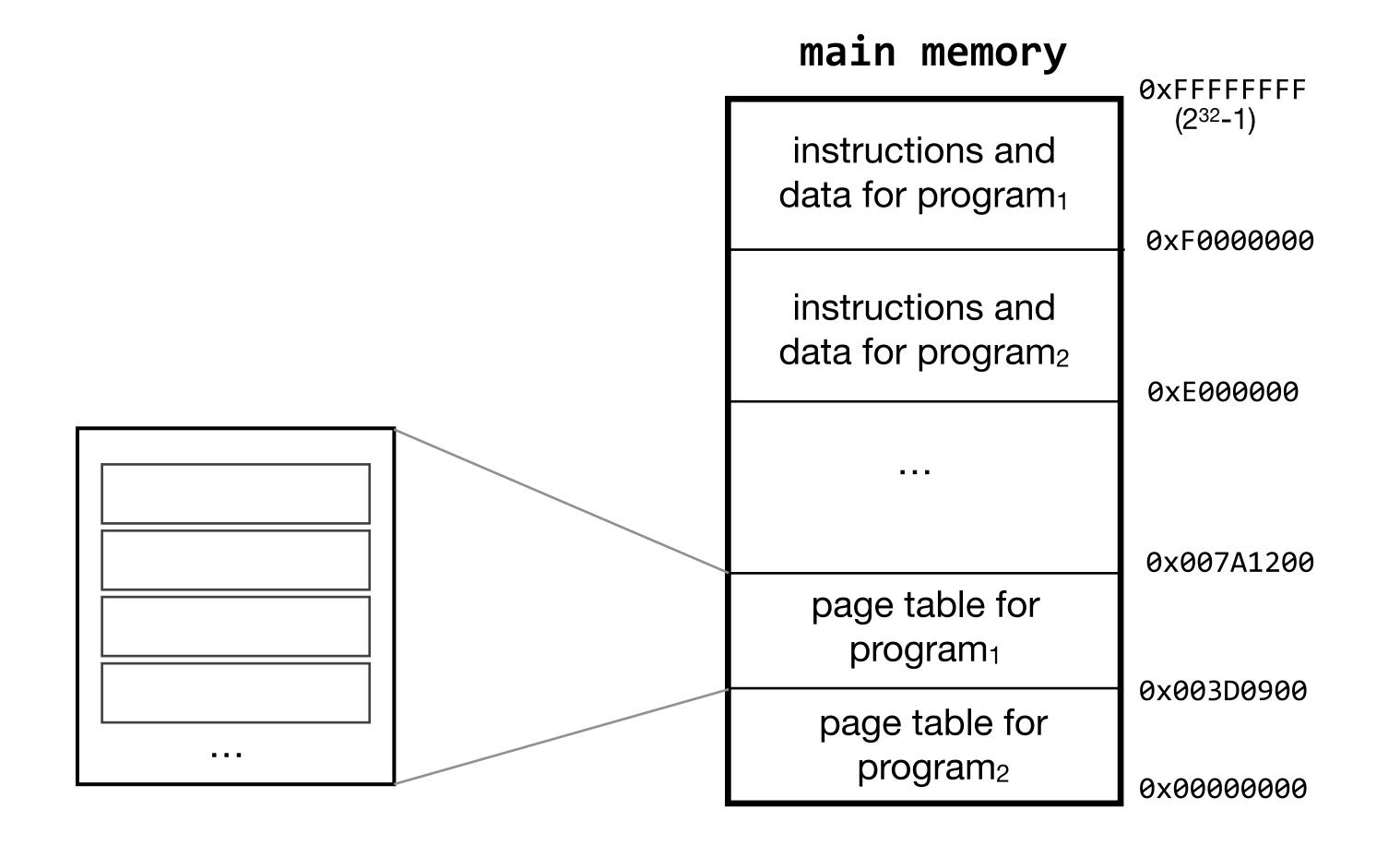


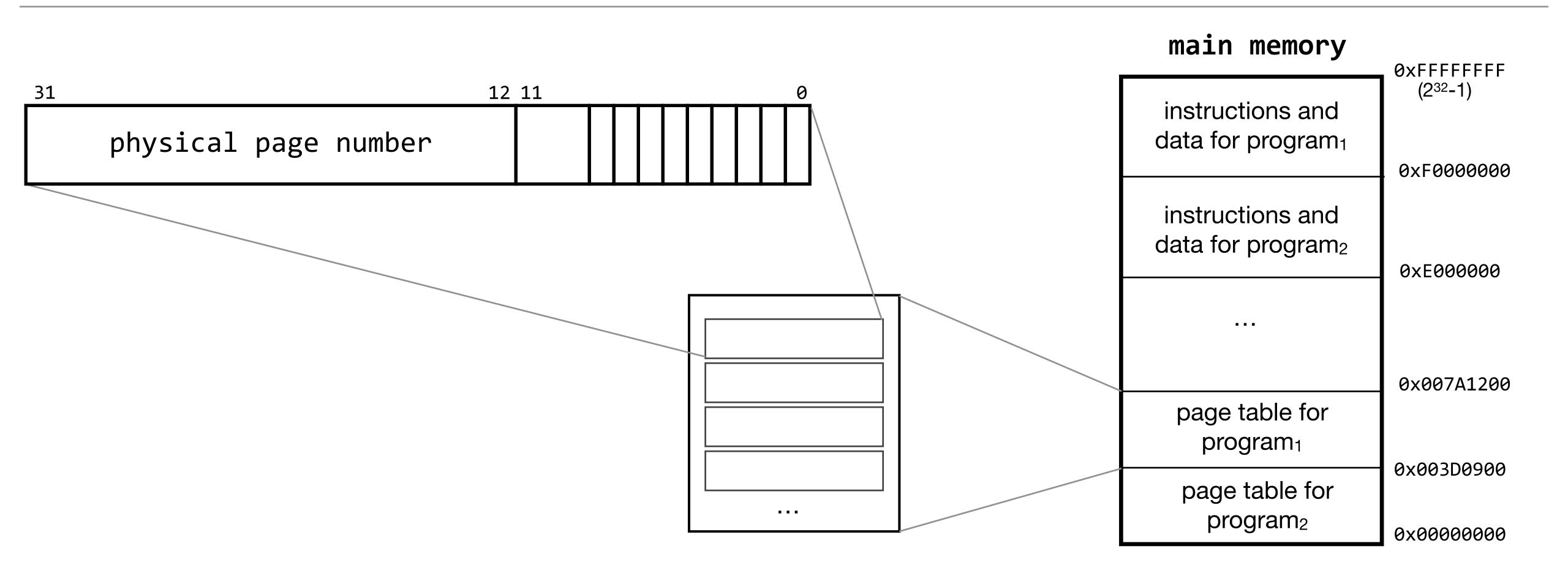
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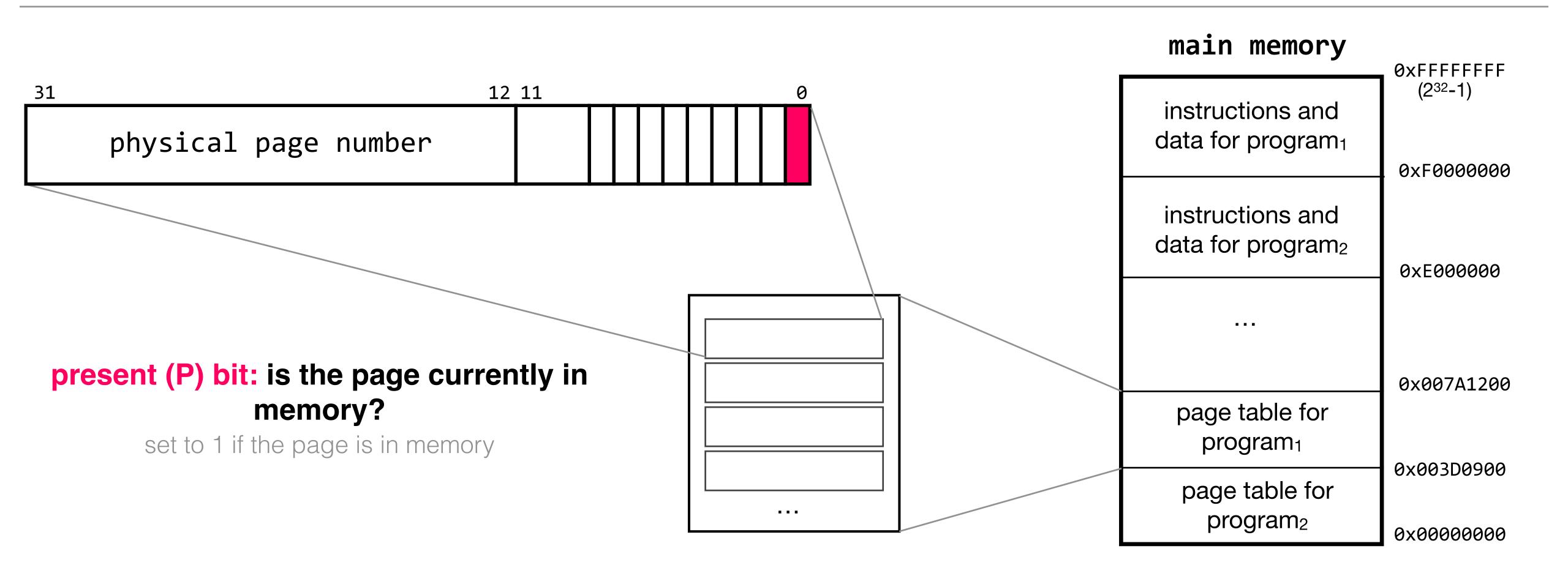
what performance issues matter here?

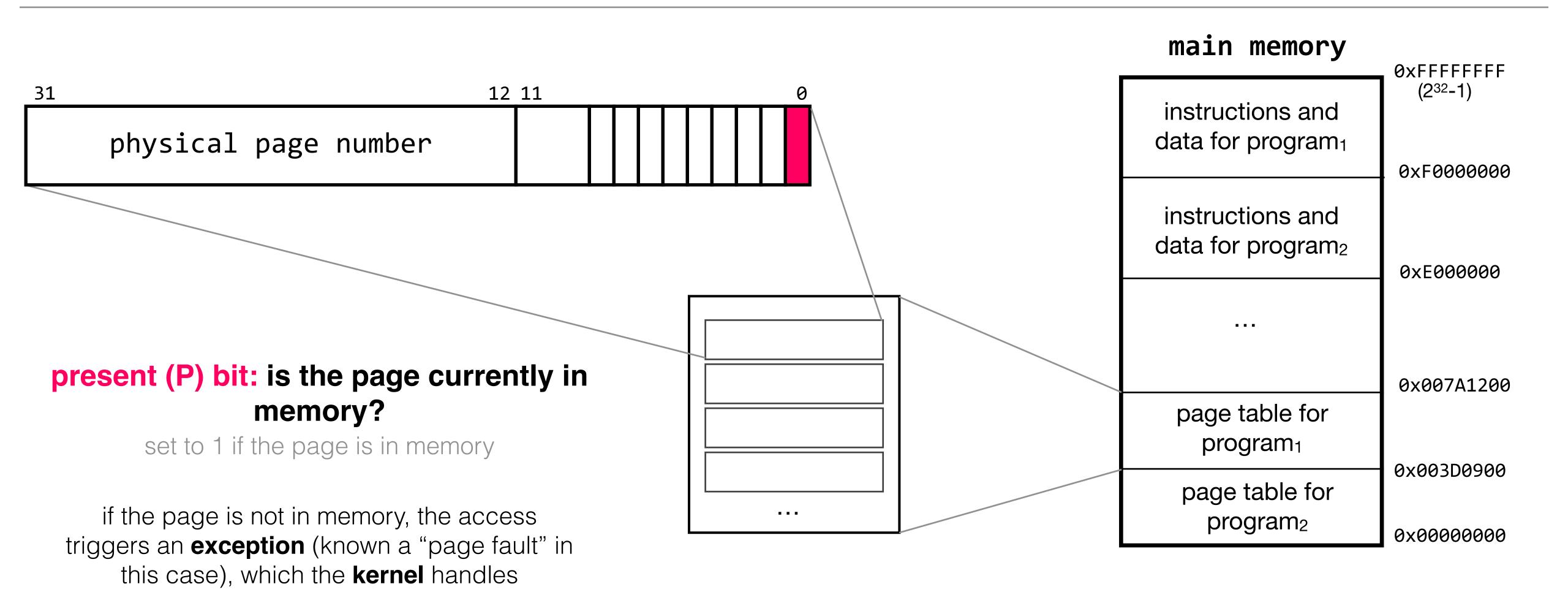


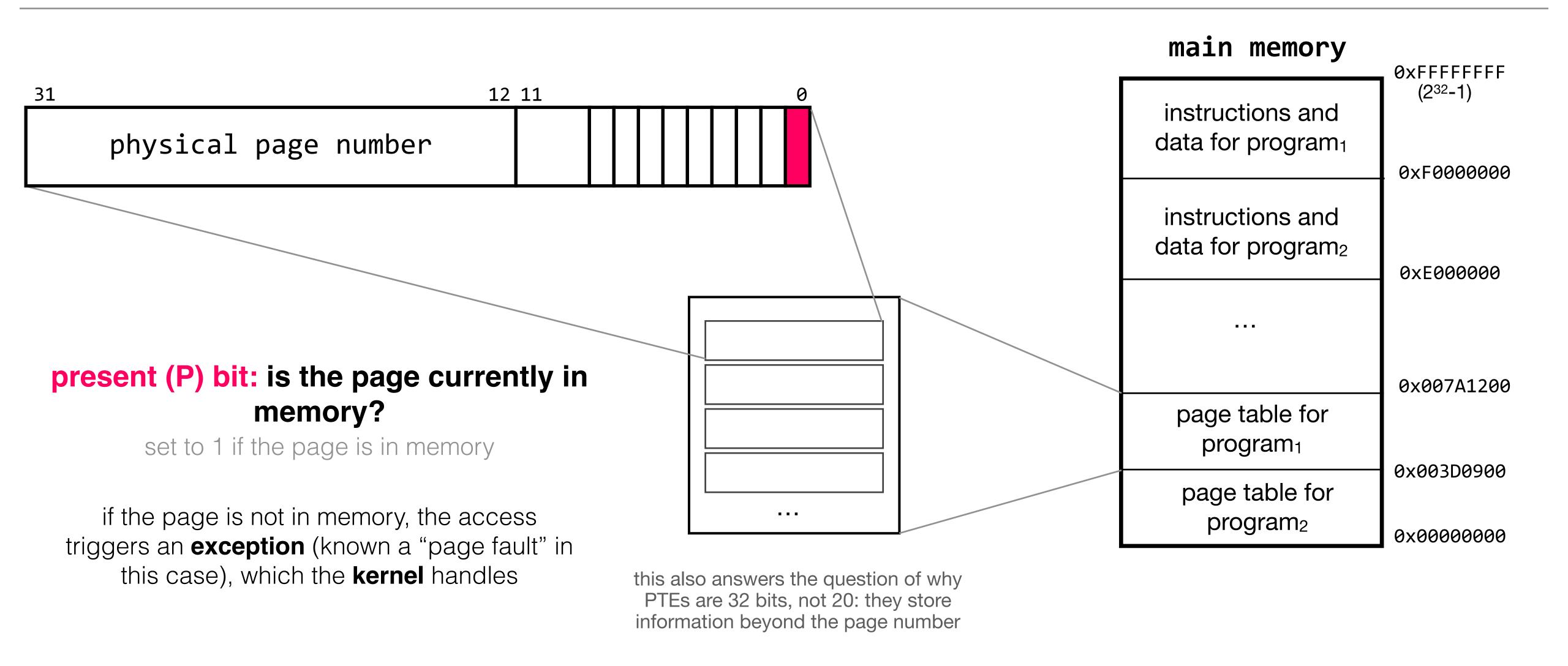












interlude: handling exceptions

(such as page faults)

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// special instruction that calls the exception handler for exception x
exception(x):
   // switch from user mode to kernel mode
   // call the handler for this particular exception
   // switch from kernel mode to user mode
```

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the operating system's kernel manages page faults and other exceptions

```
// special instruction that calls the exception handler for exception x
exception(x):
   U/K bit = K
   // call the handler for this particular exception
   U/K bit = U
```

the processor stores a **user/kernel (U/K) bit** that indicates whether its operating in user mode or kernel mode. this bit helps the processor control access to certain kernel-specific actions

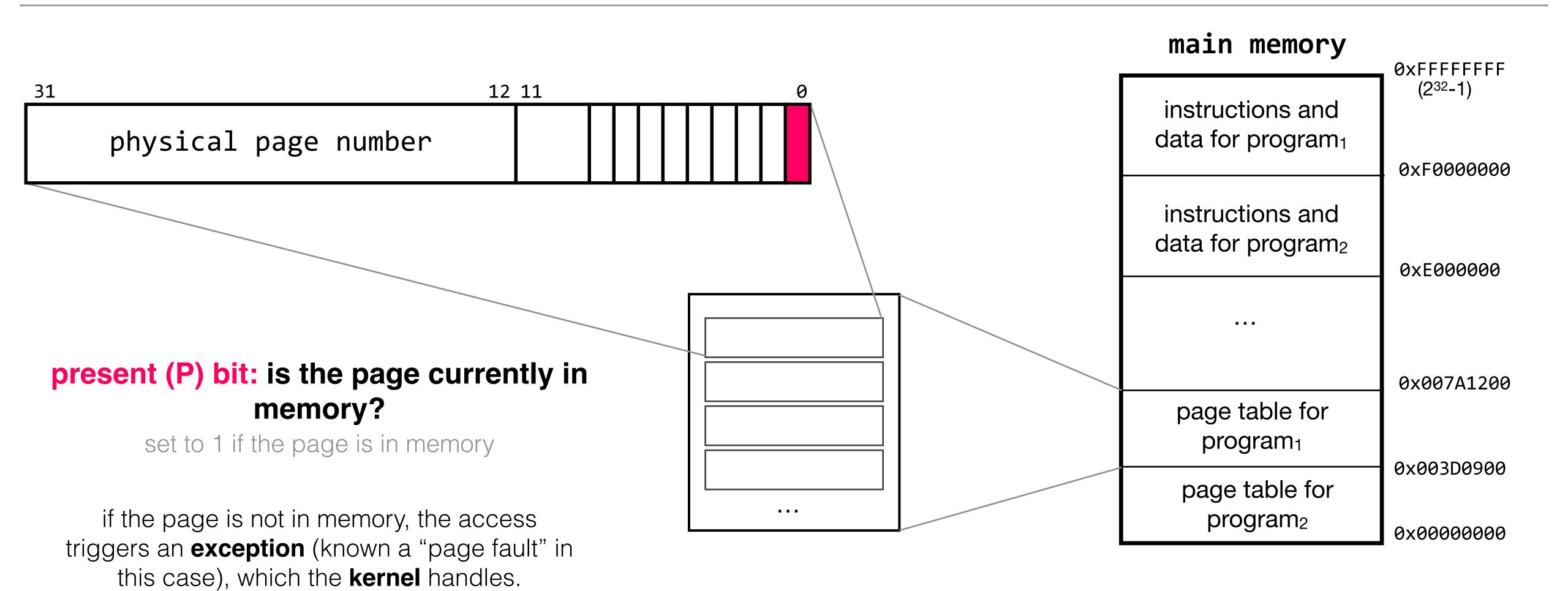
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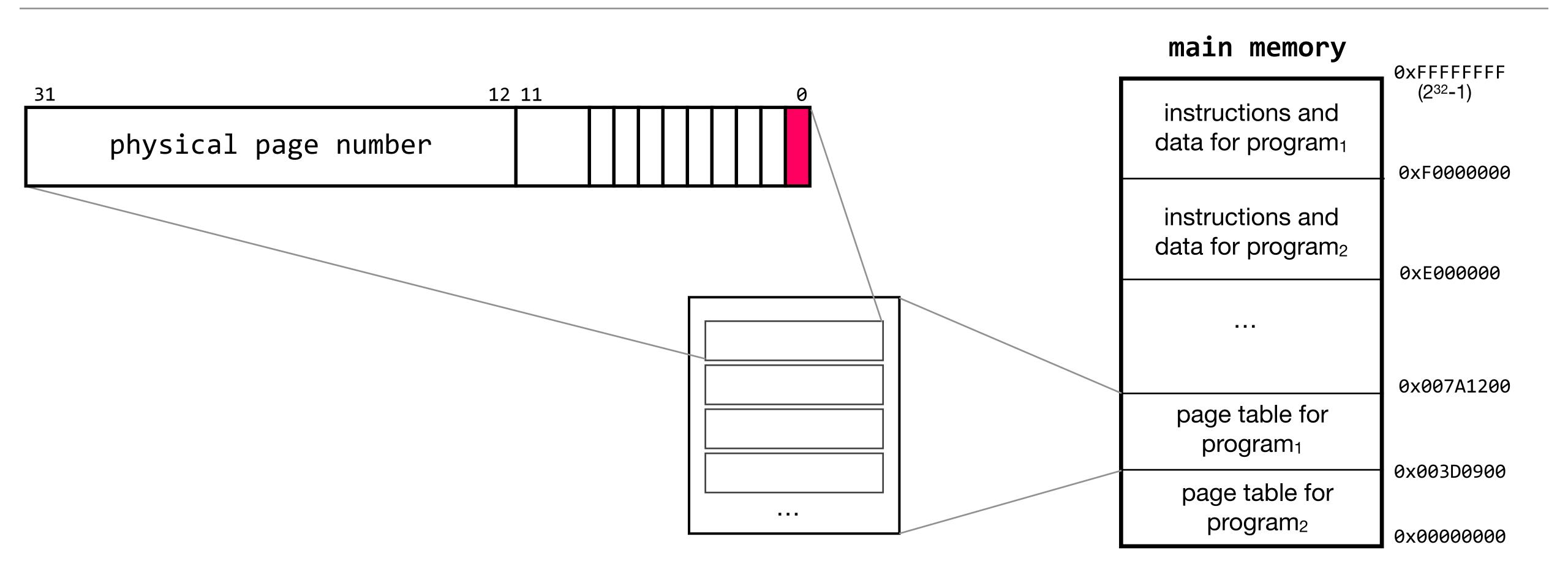
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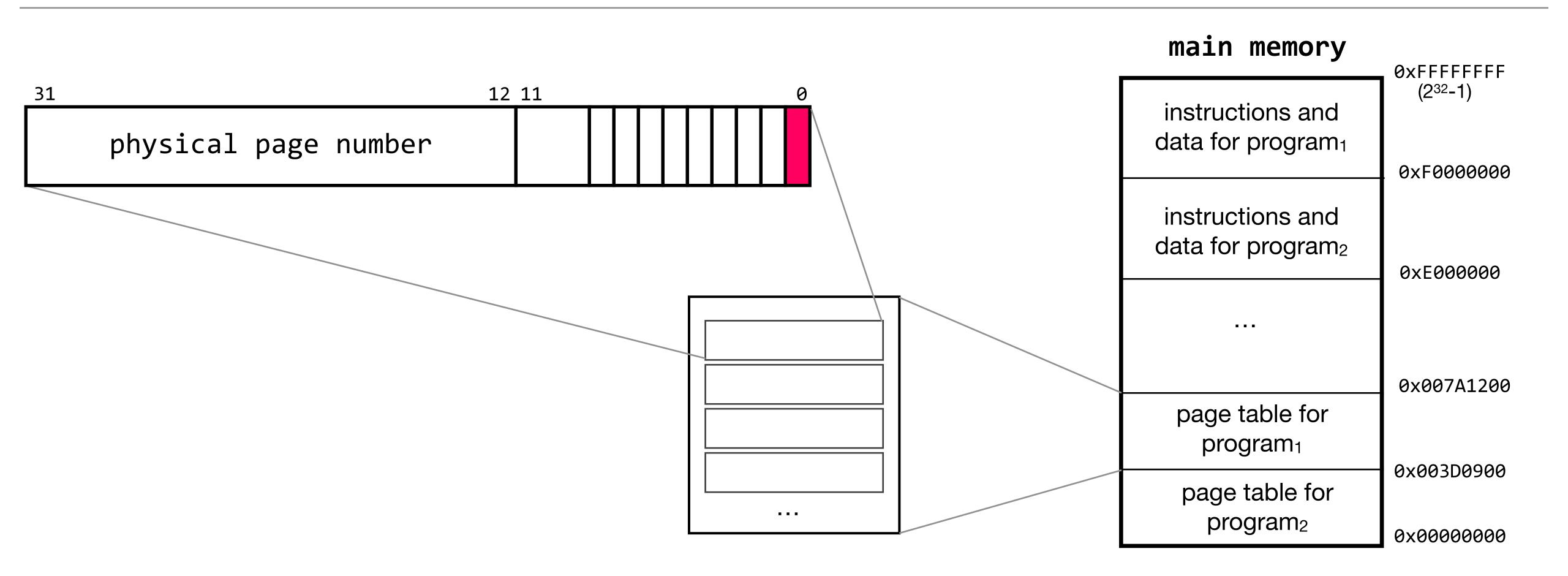
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each handler is different. as an example, the page-fault handler would take care of bringing the requested page into memory

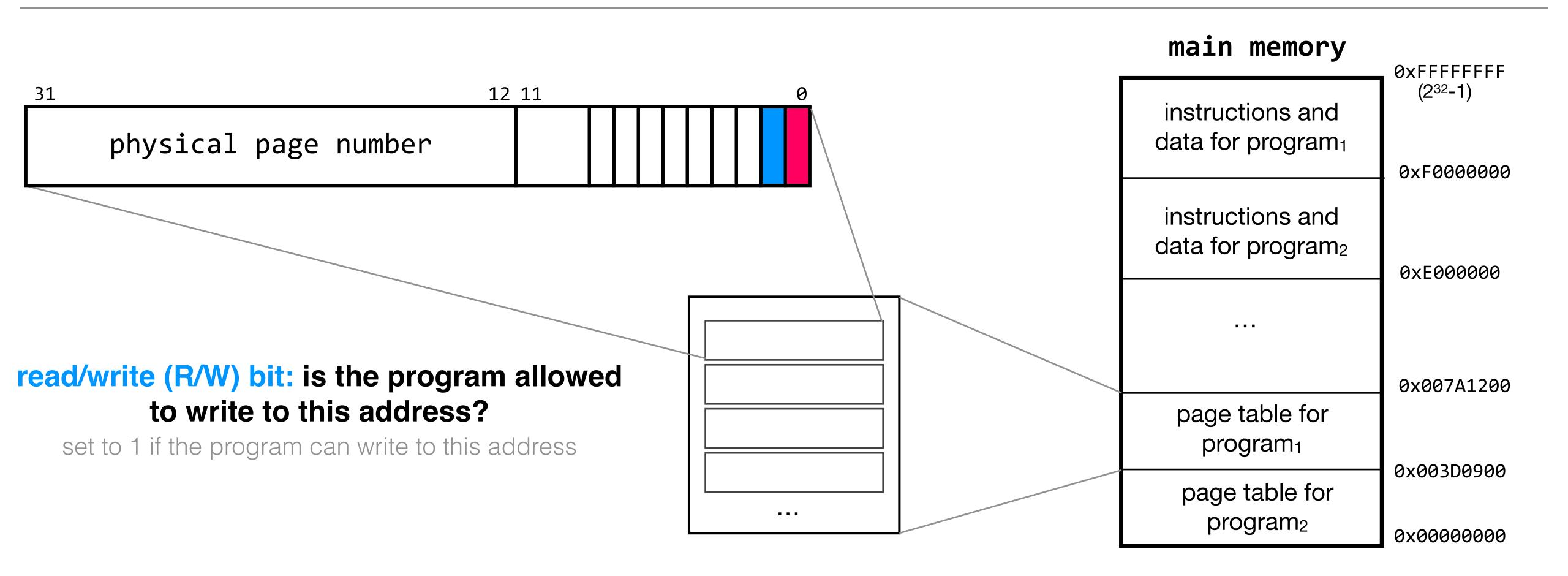




after all, it's conceivable that we want program₁ to be able to read some data, but not to modify it

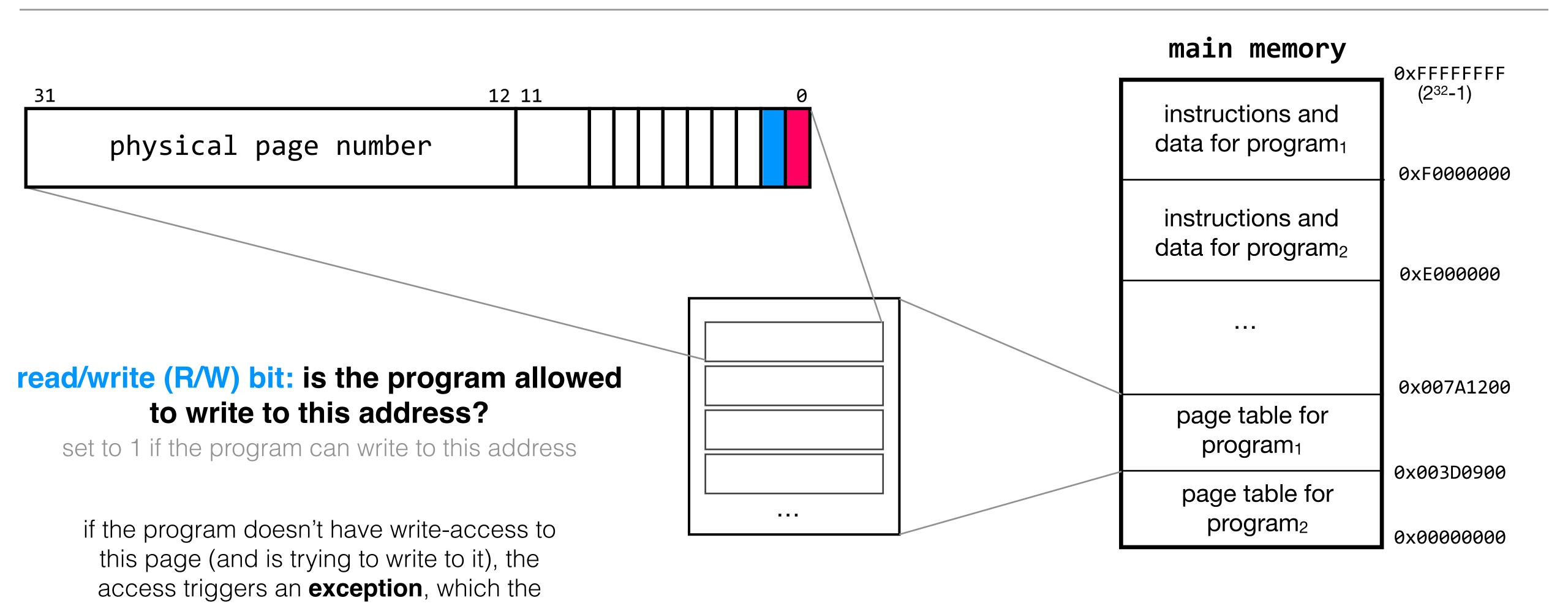


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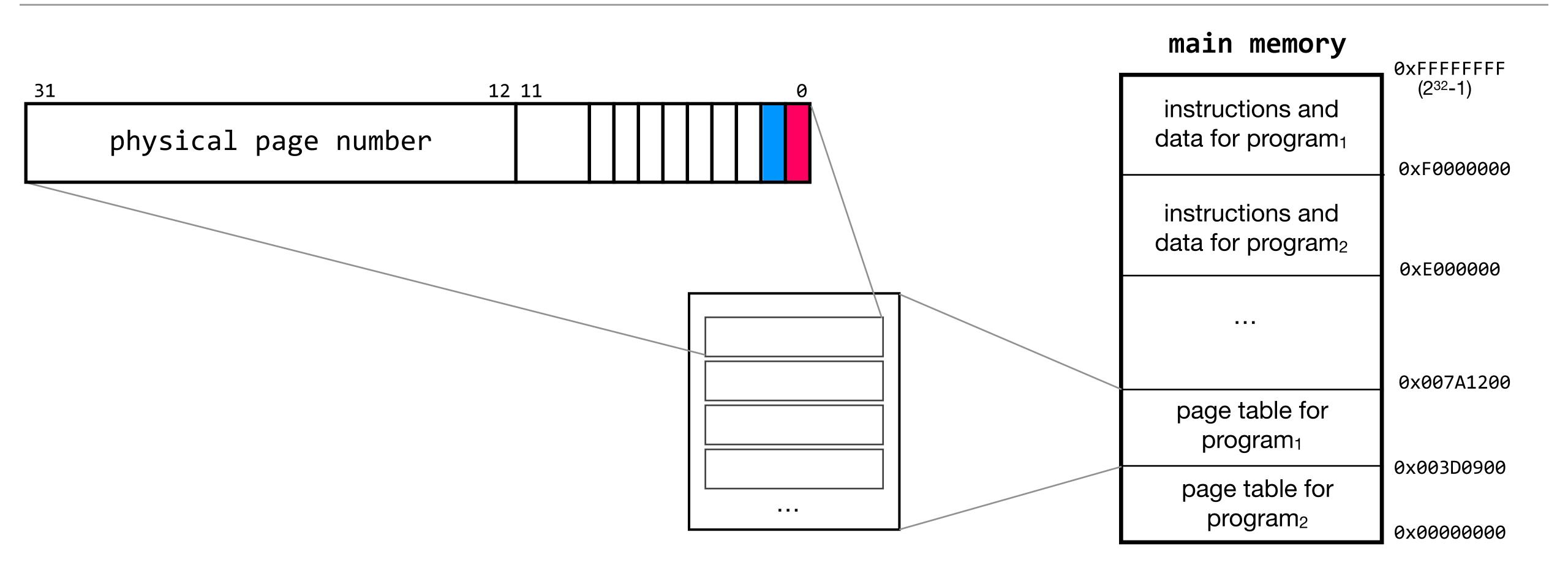


kernel handles

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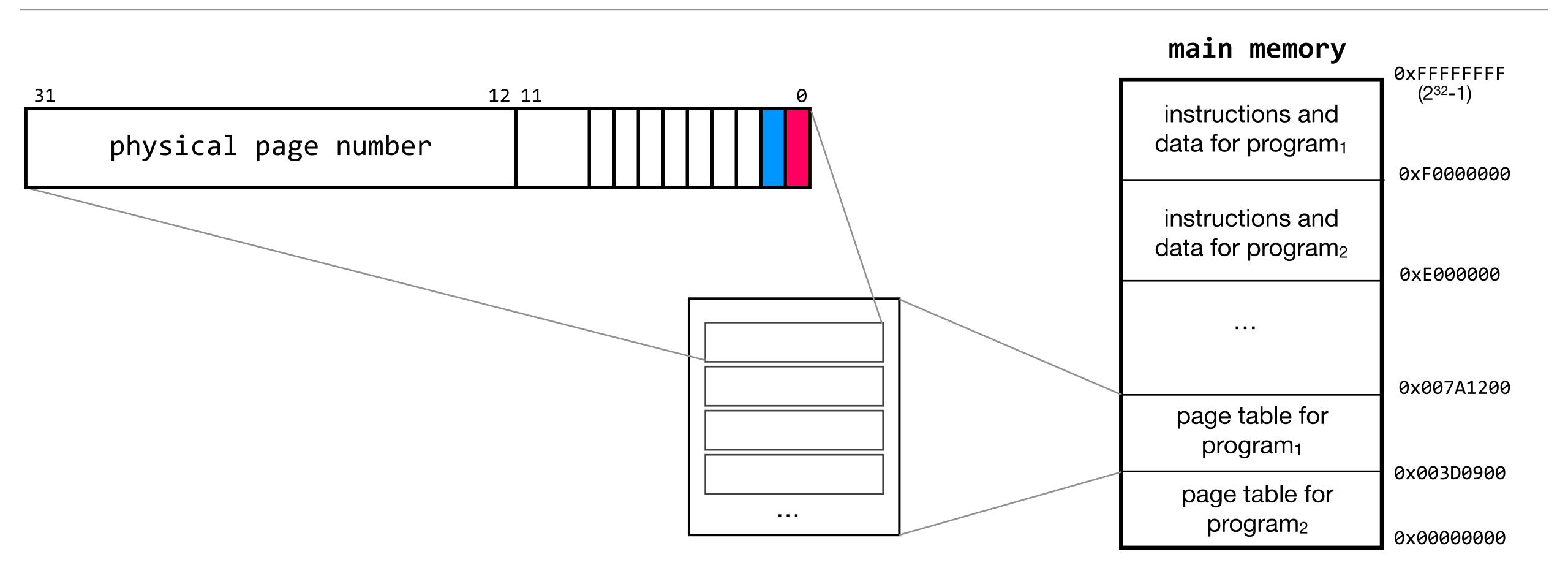


what happens if a program tries to access memory that only the kernel should have access to?



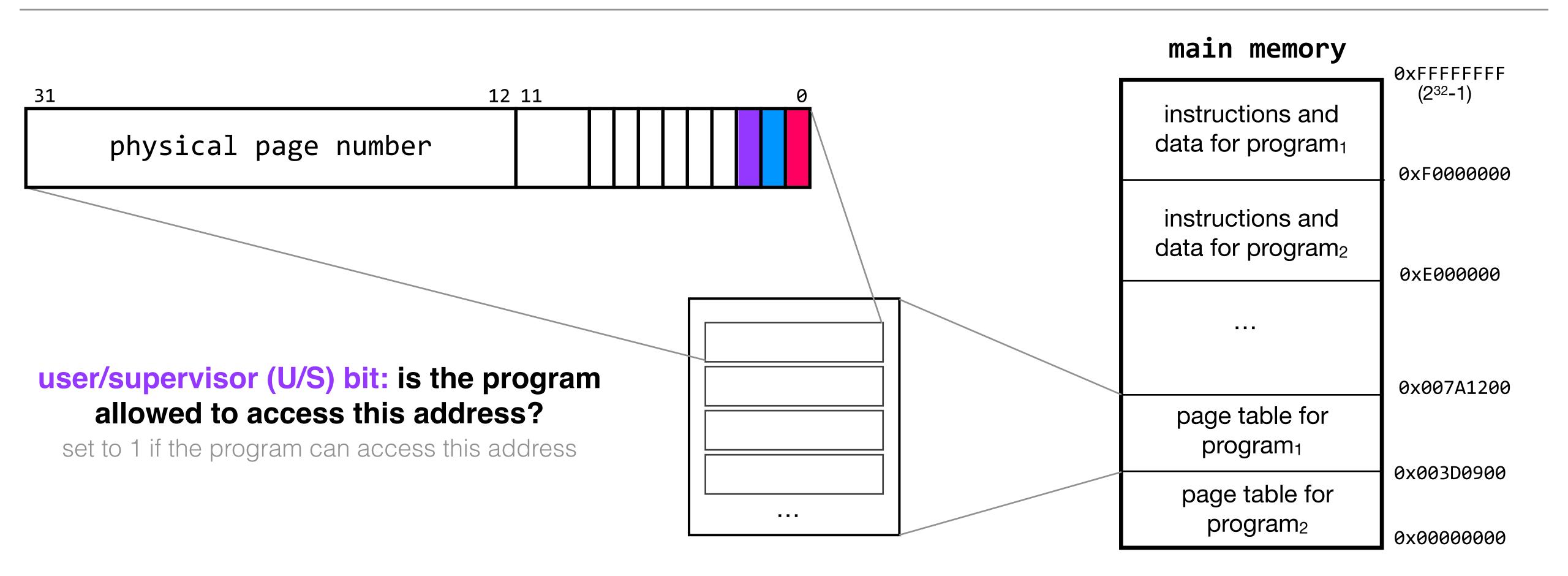
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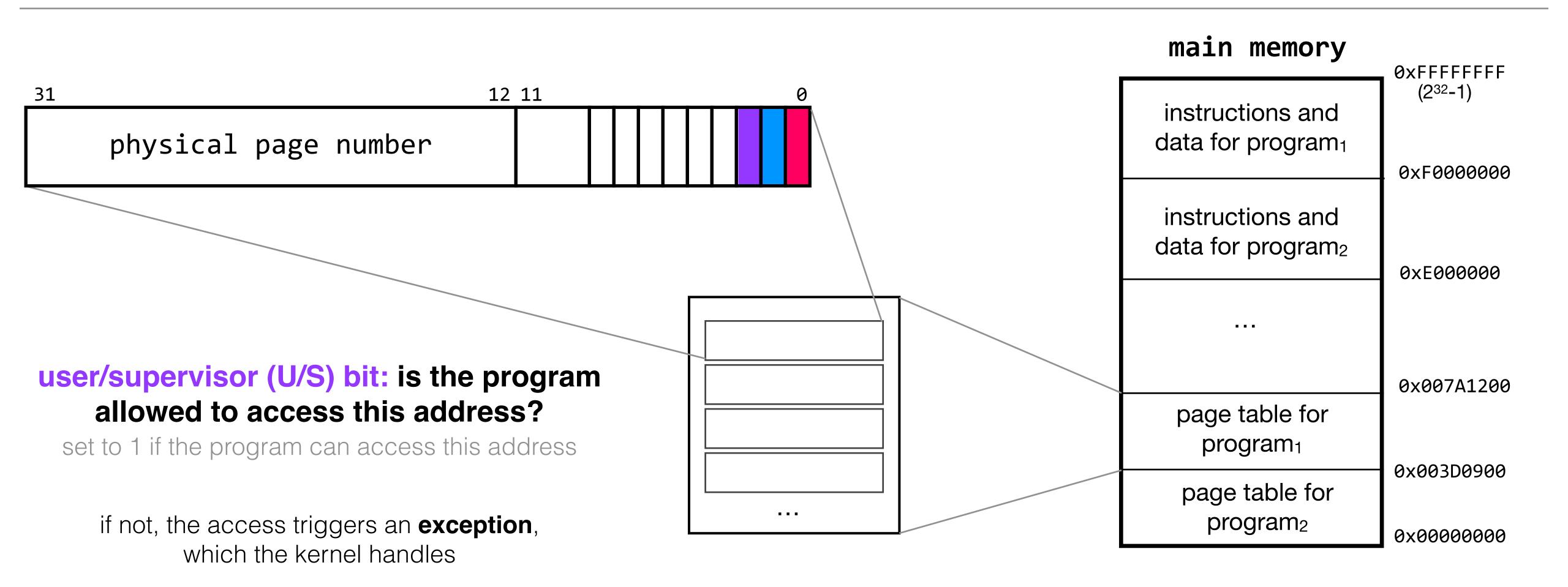
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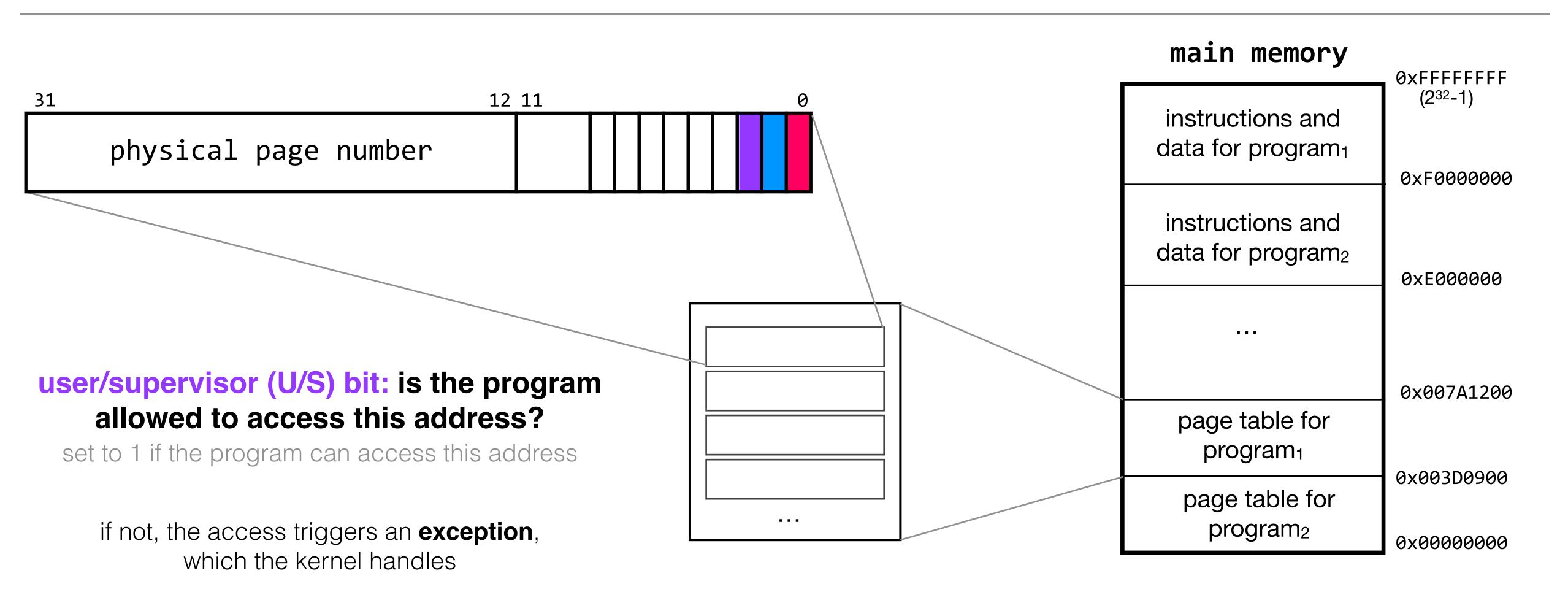
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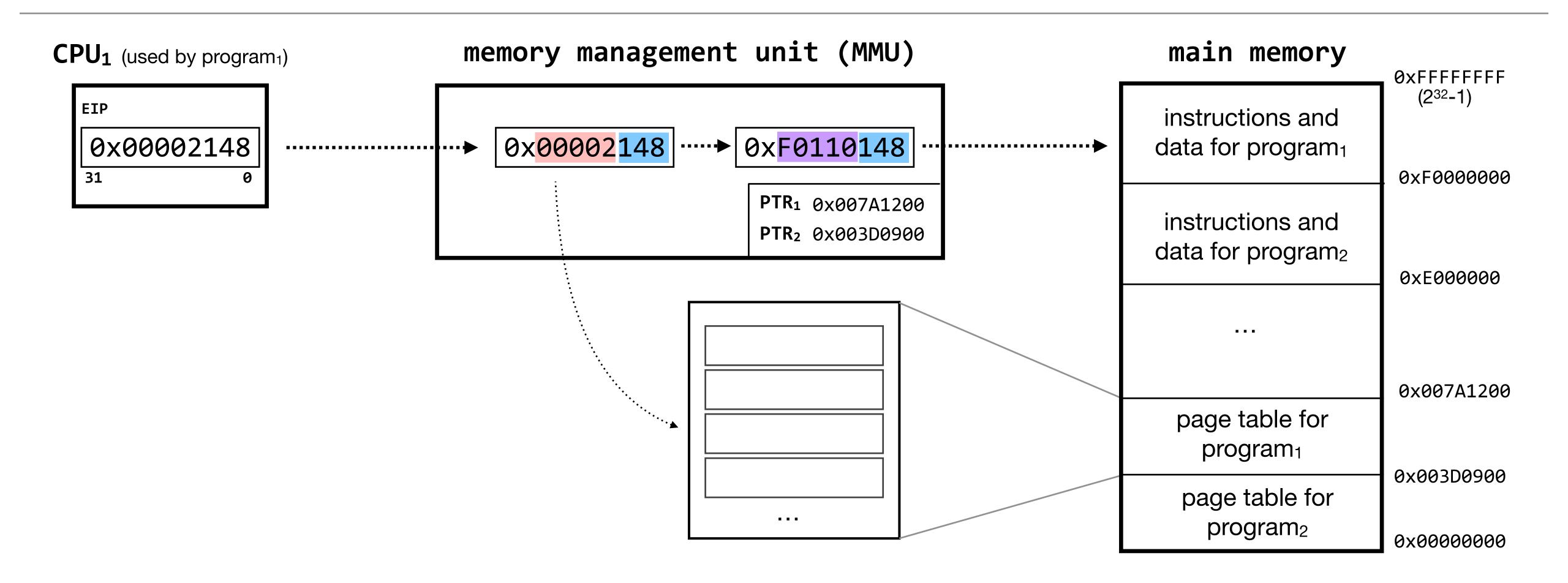


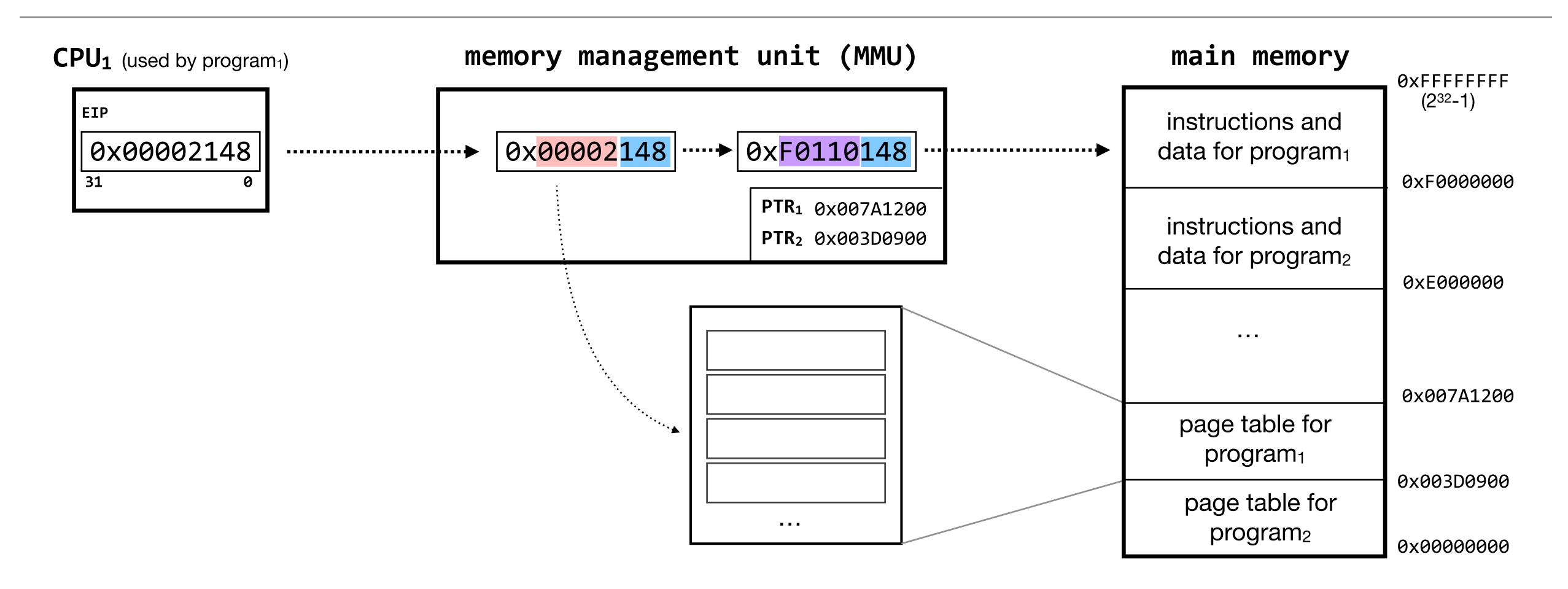
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without this last piece, a determined program could still attempt to circumvent modularity by doing things such as modifying the page-table registers

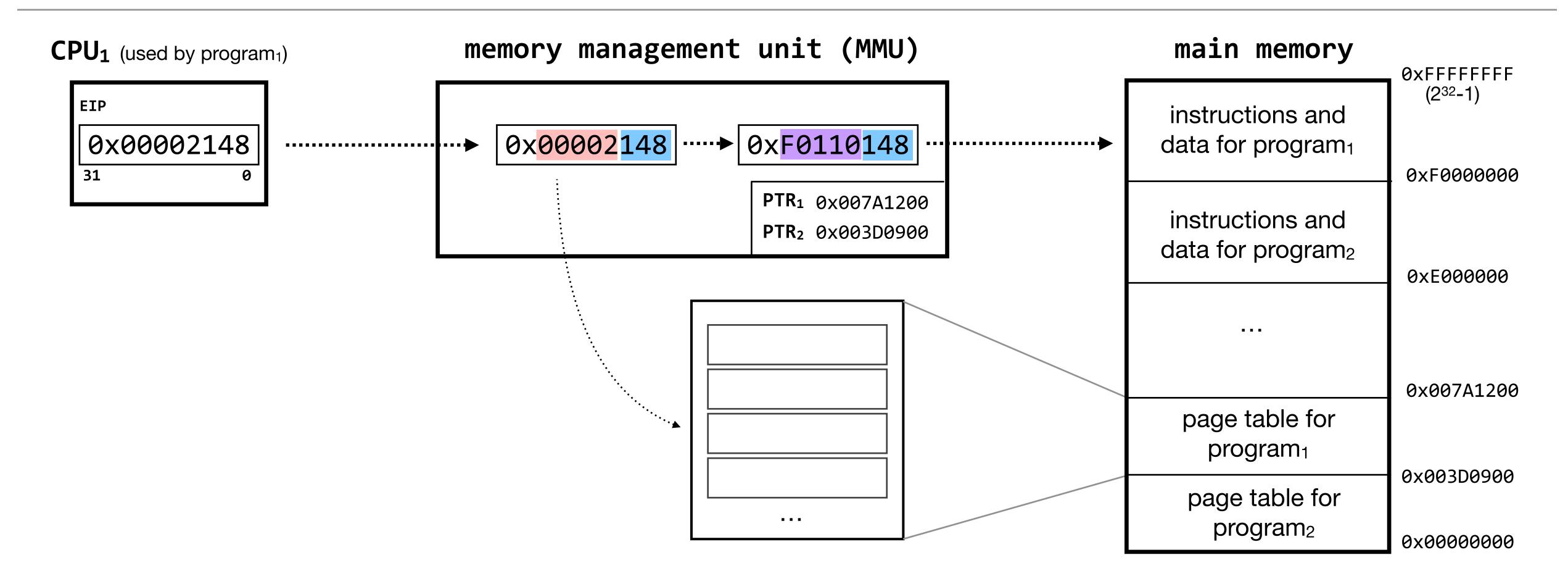




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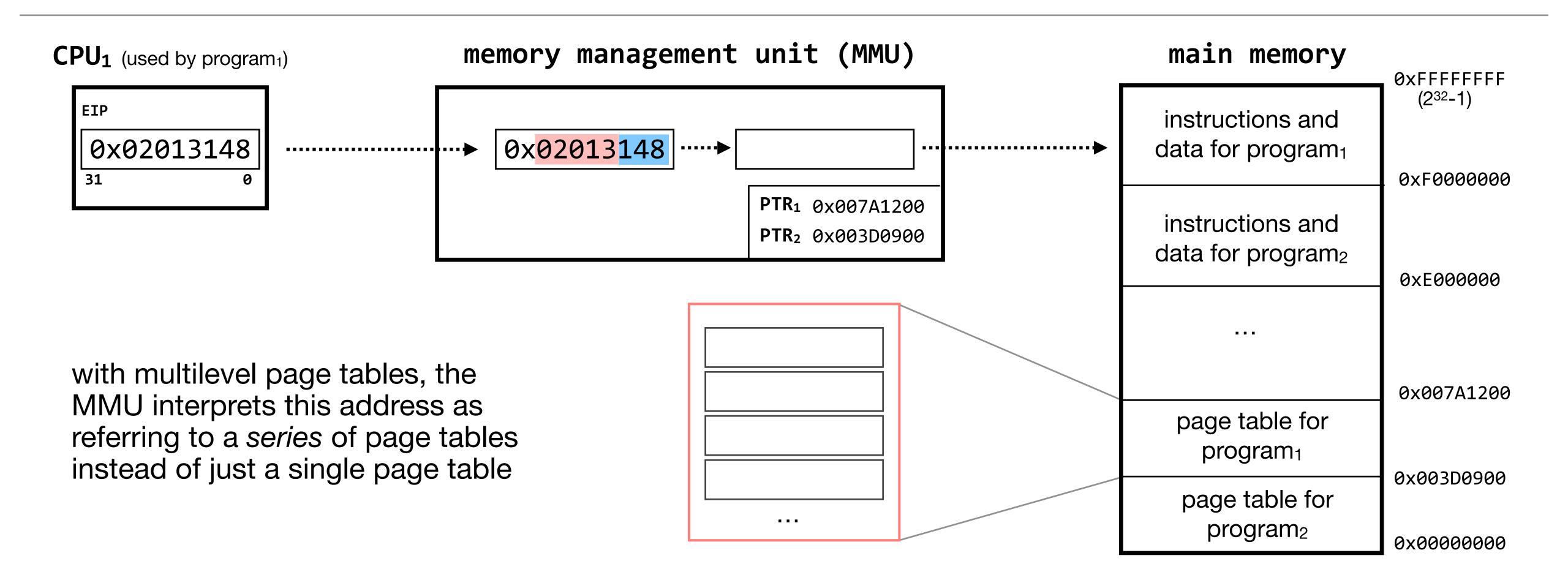
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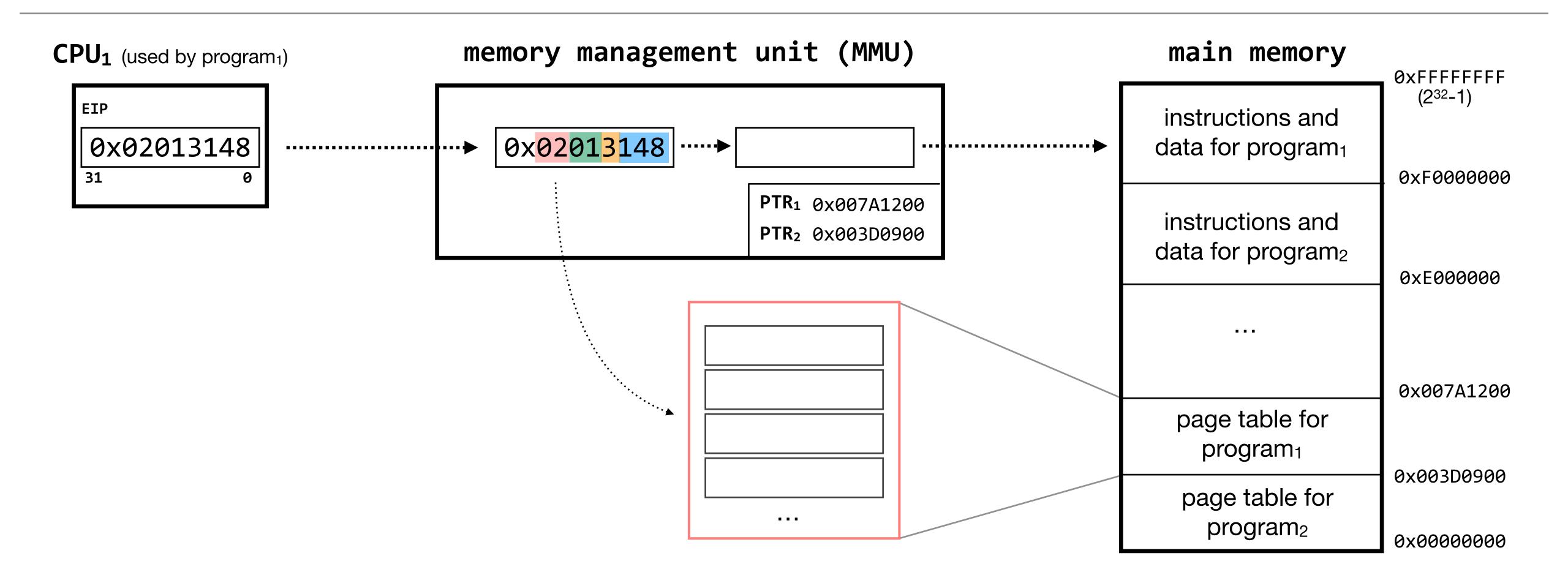
performance issue #1: page tables are allocated contiguously in memory so that access into them is extremely fast; this means that every page table is 4MB, even if the program only needs to make a few memory accesses

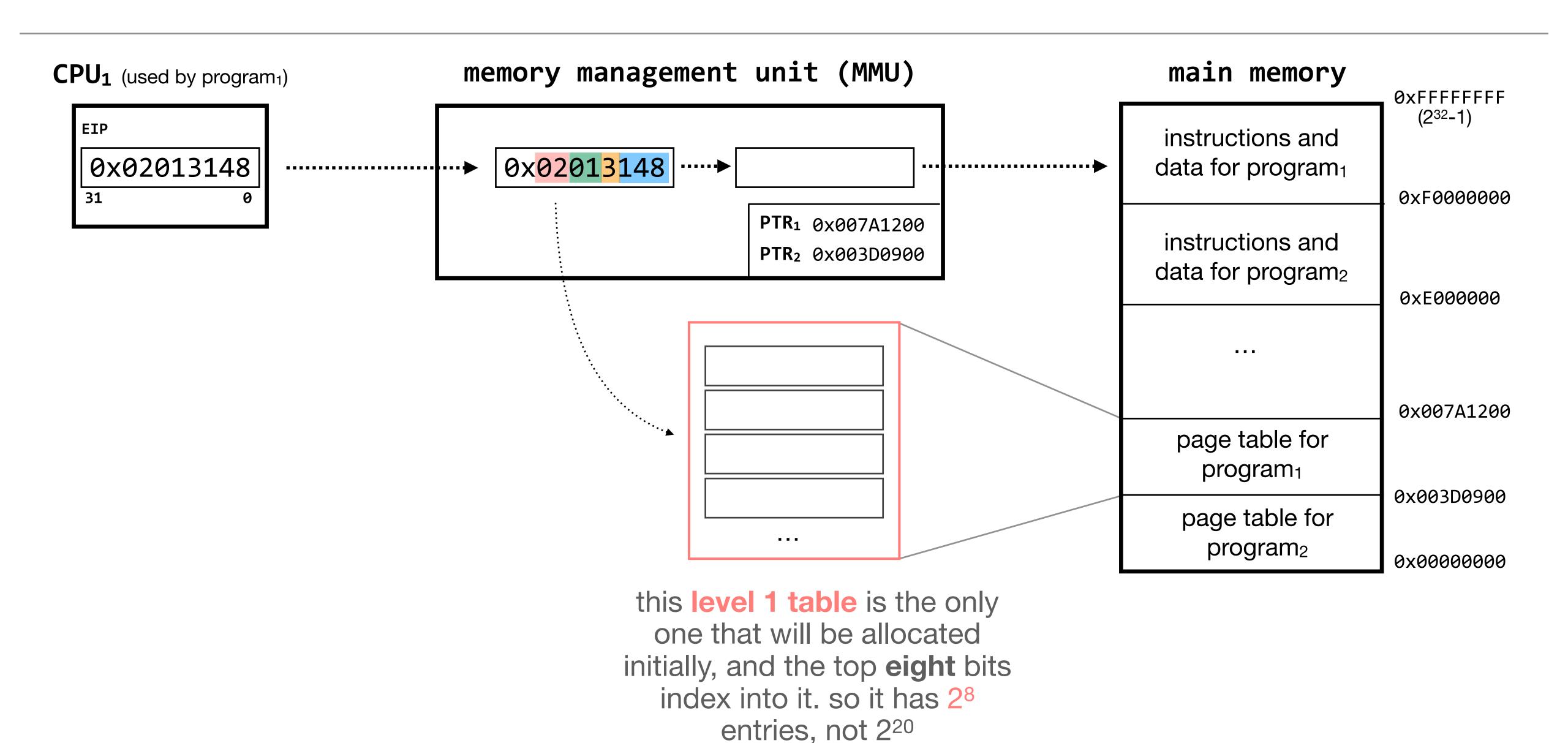


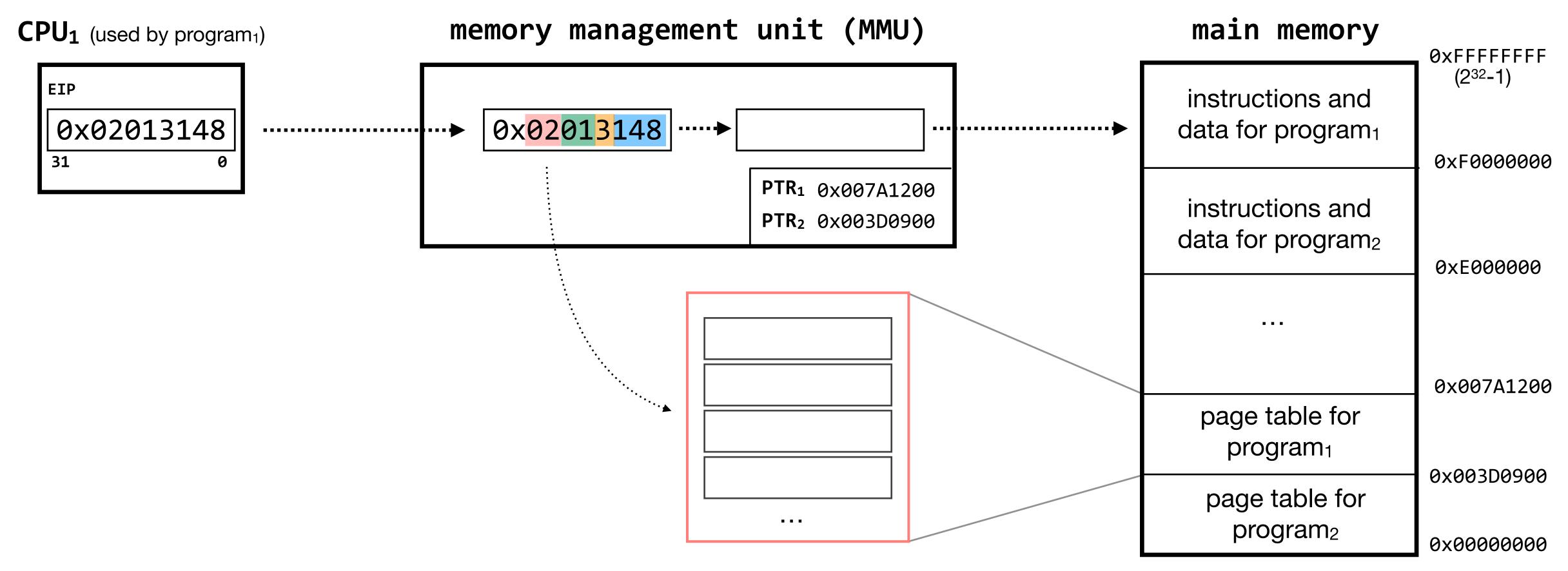
2²⁰ virtual addresses each mapping to a 32-bit page-table entry (PTE)

→ 4MB to store this table

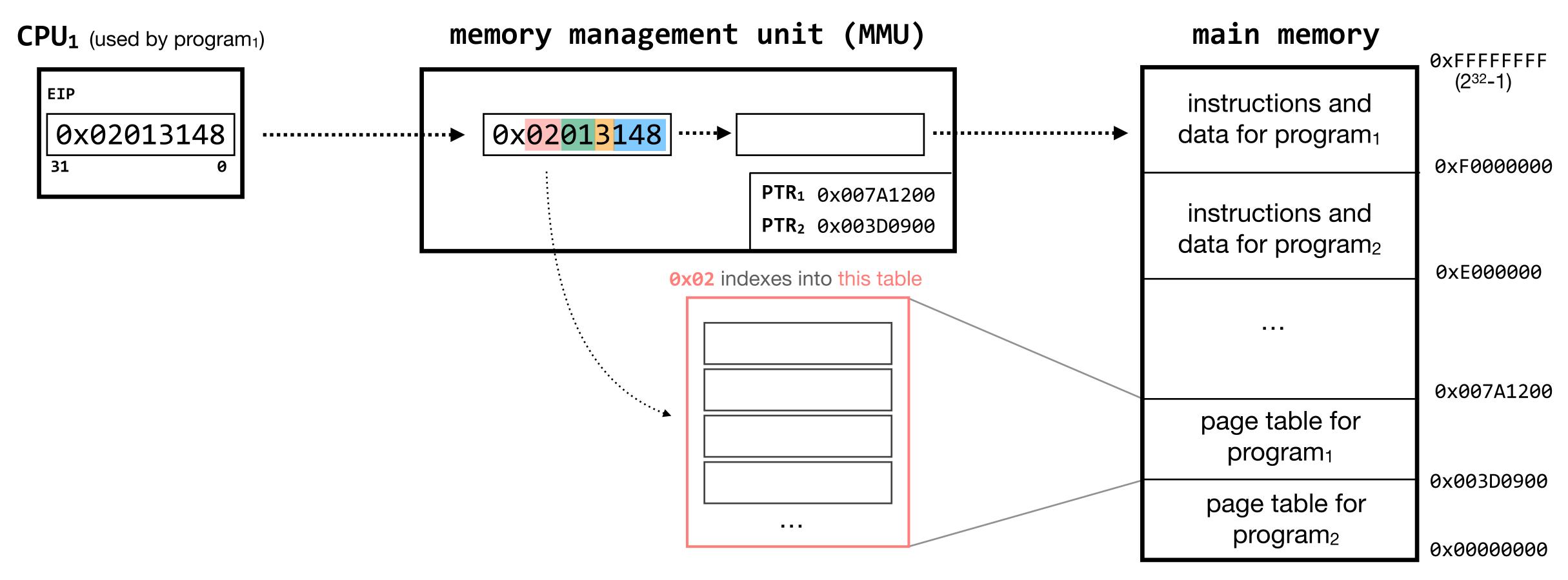




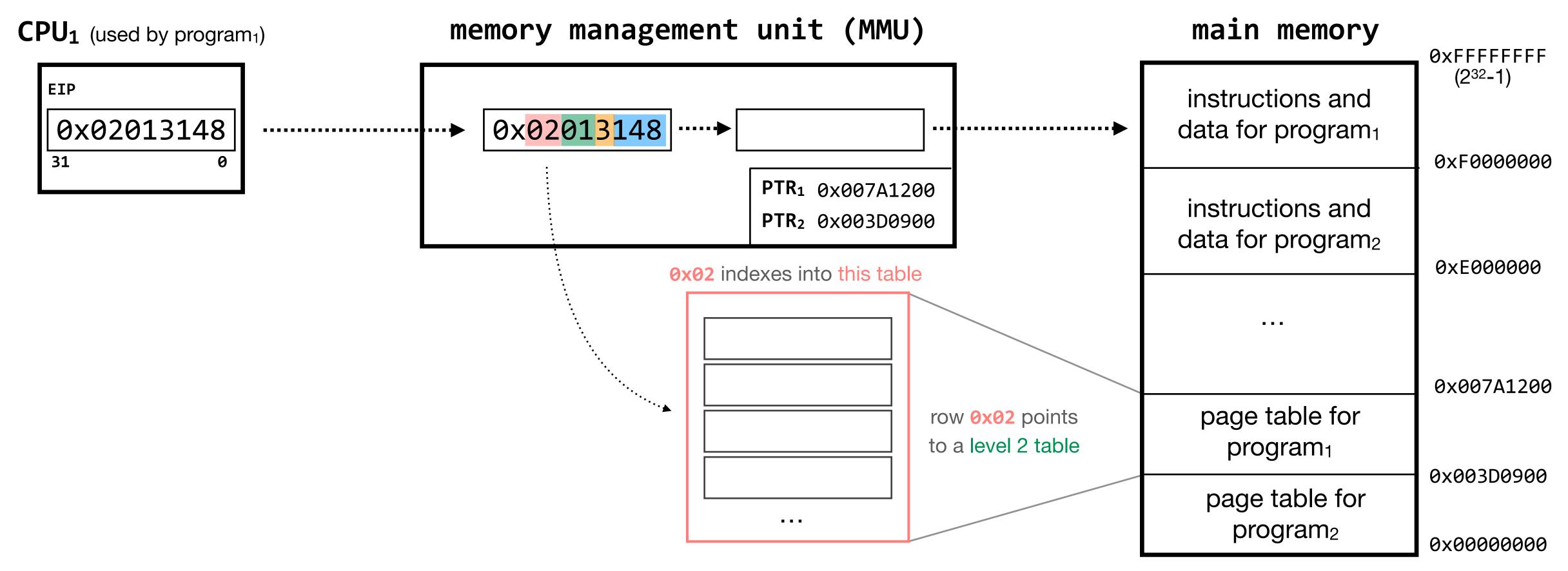




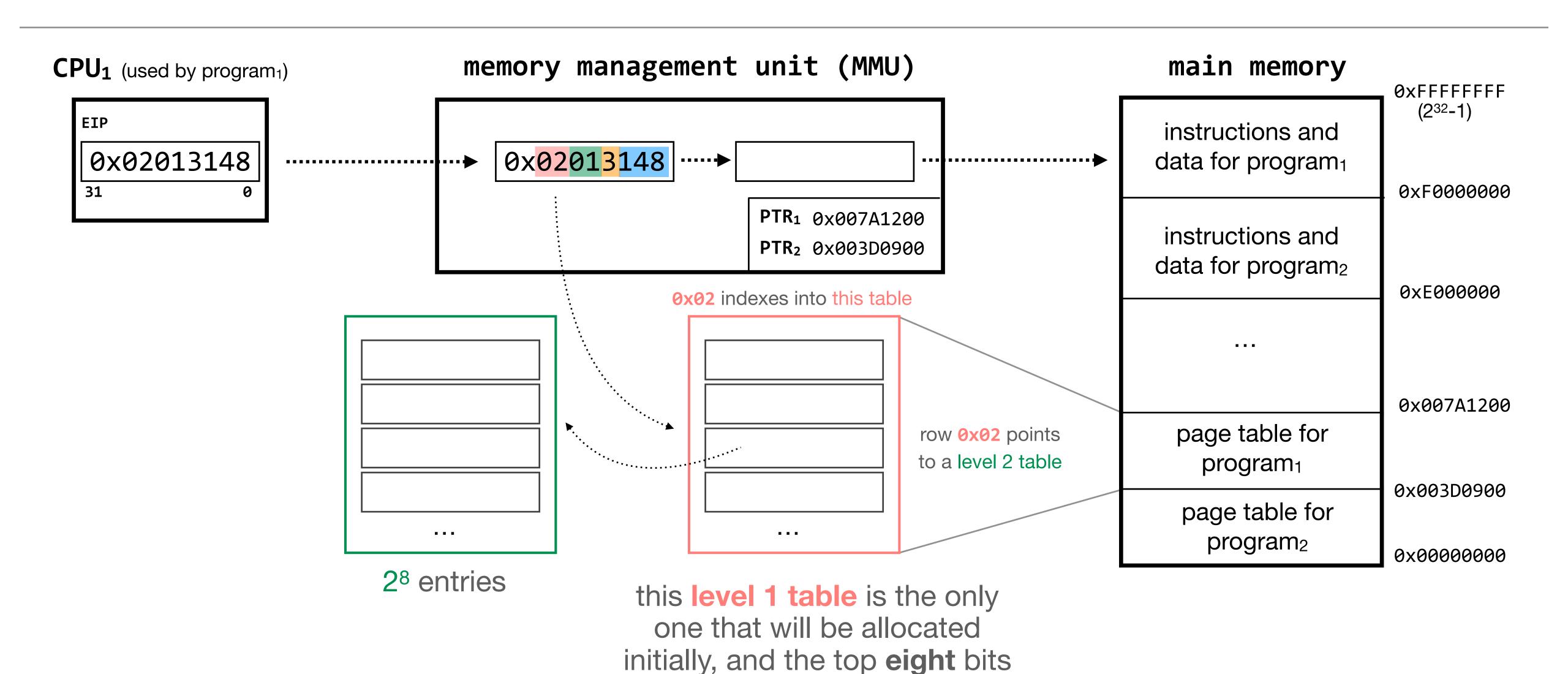
this **level 1 table** is the only one that will be allocated initially, and the top **eight** bits index into it. so it has 28 entries, not 2²⁰



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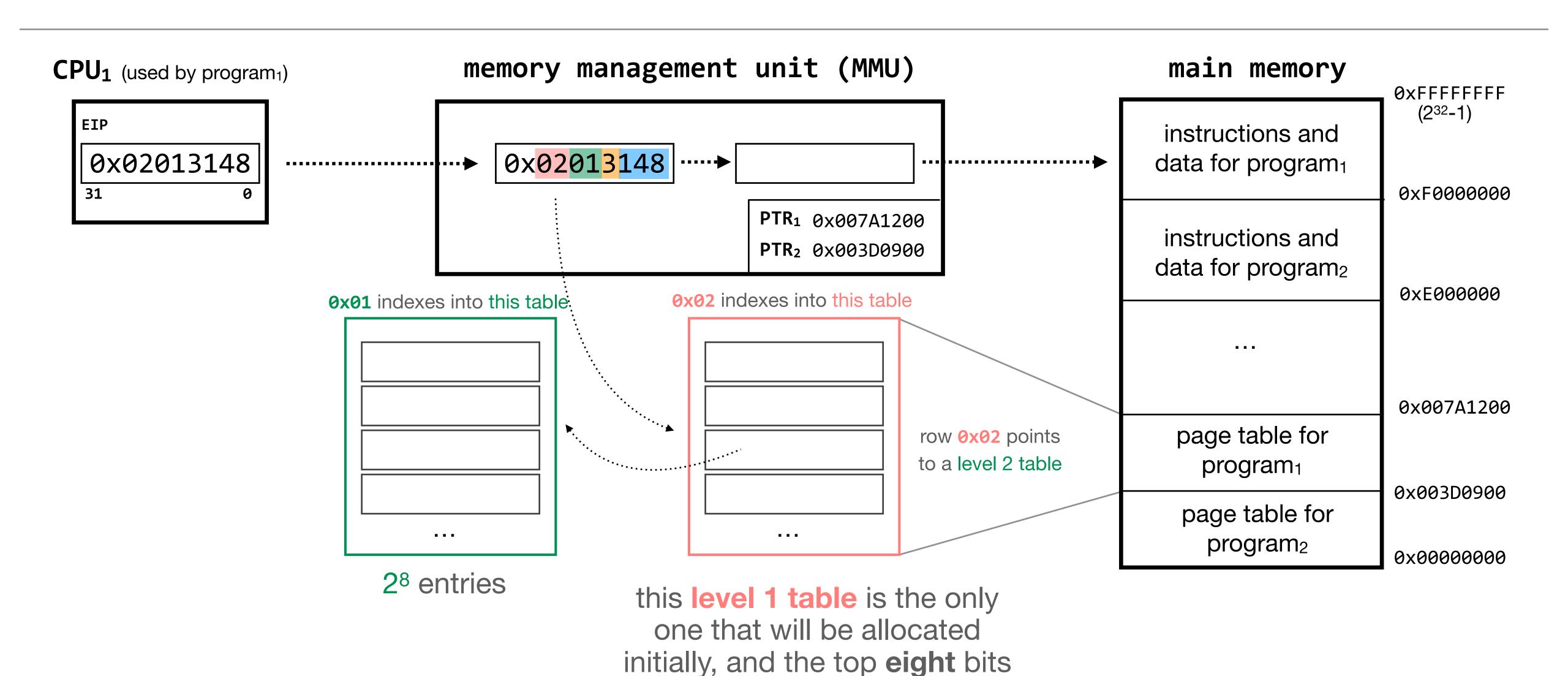


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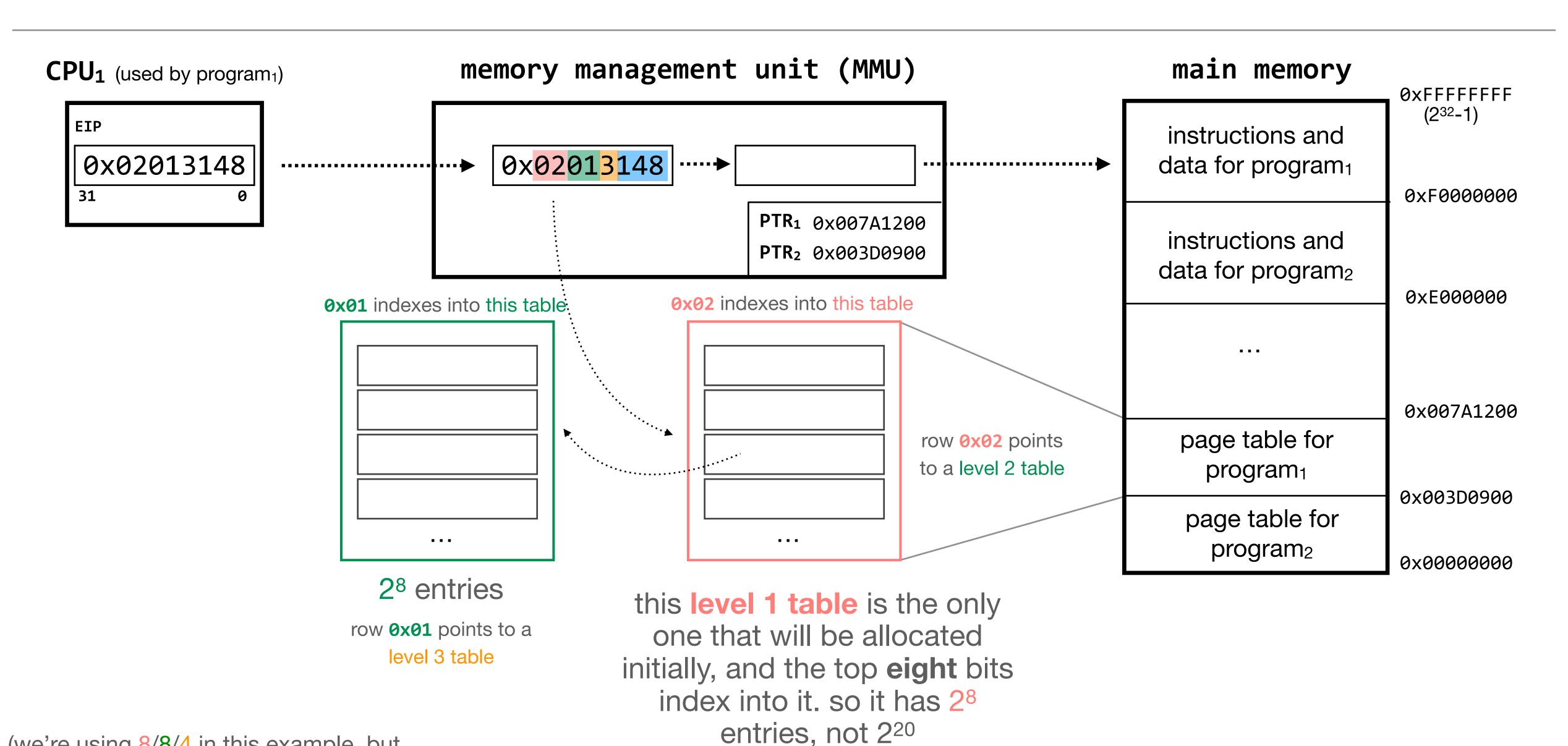
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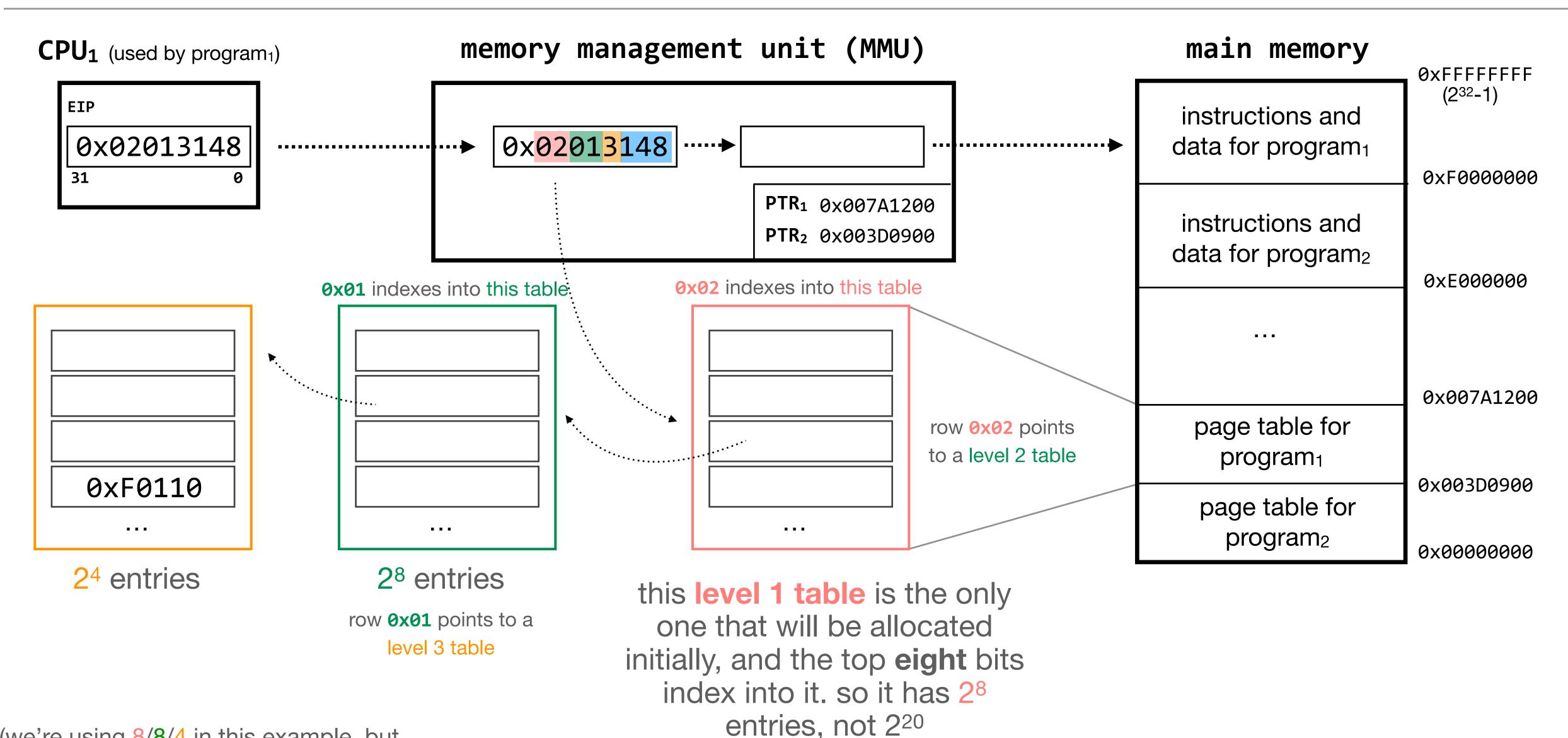


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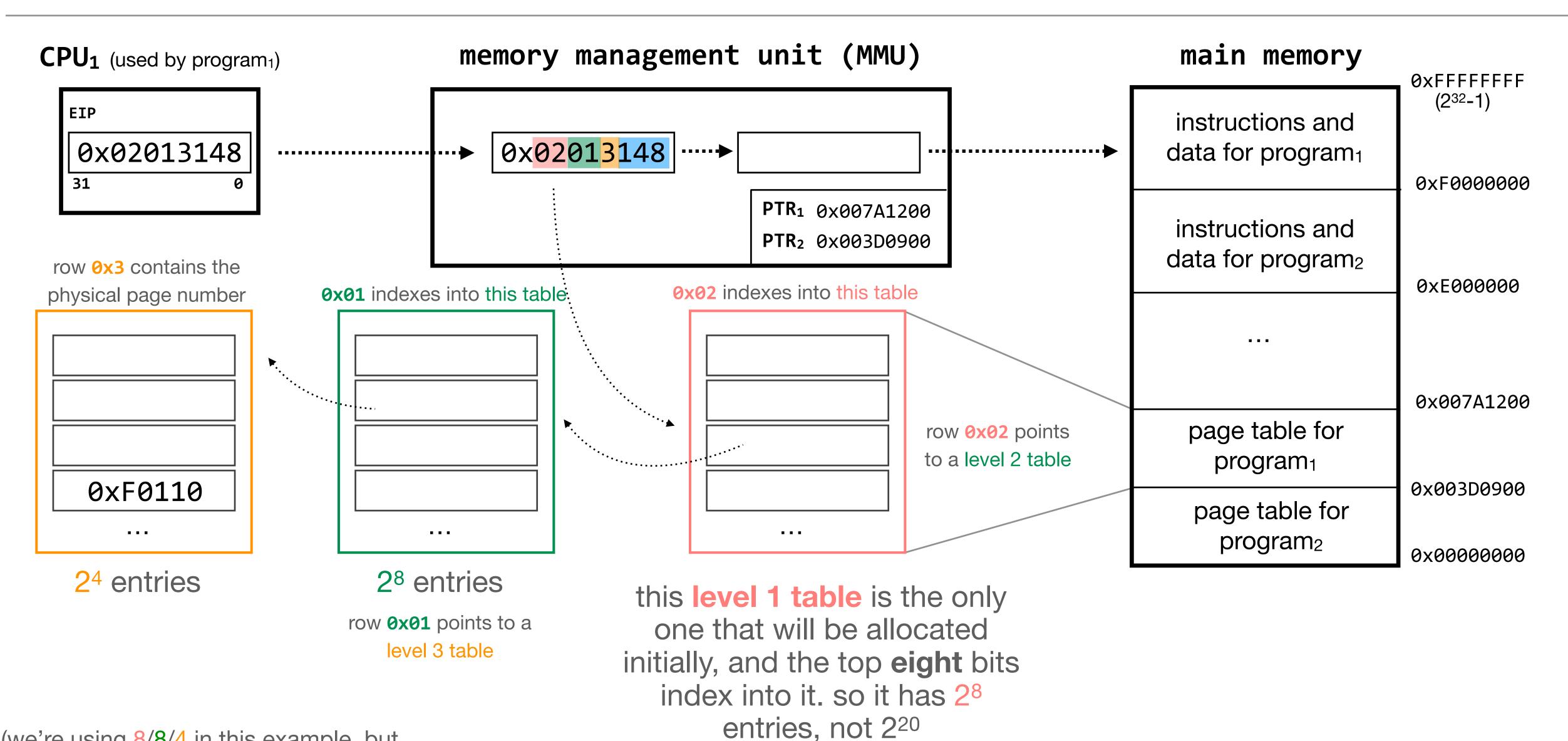
entries, not 2²⁰



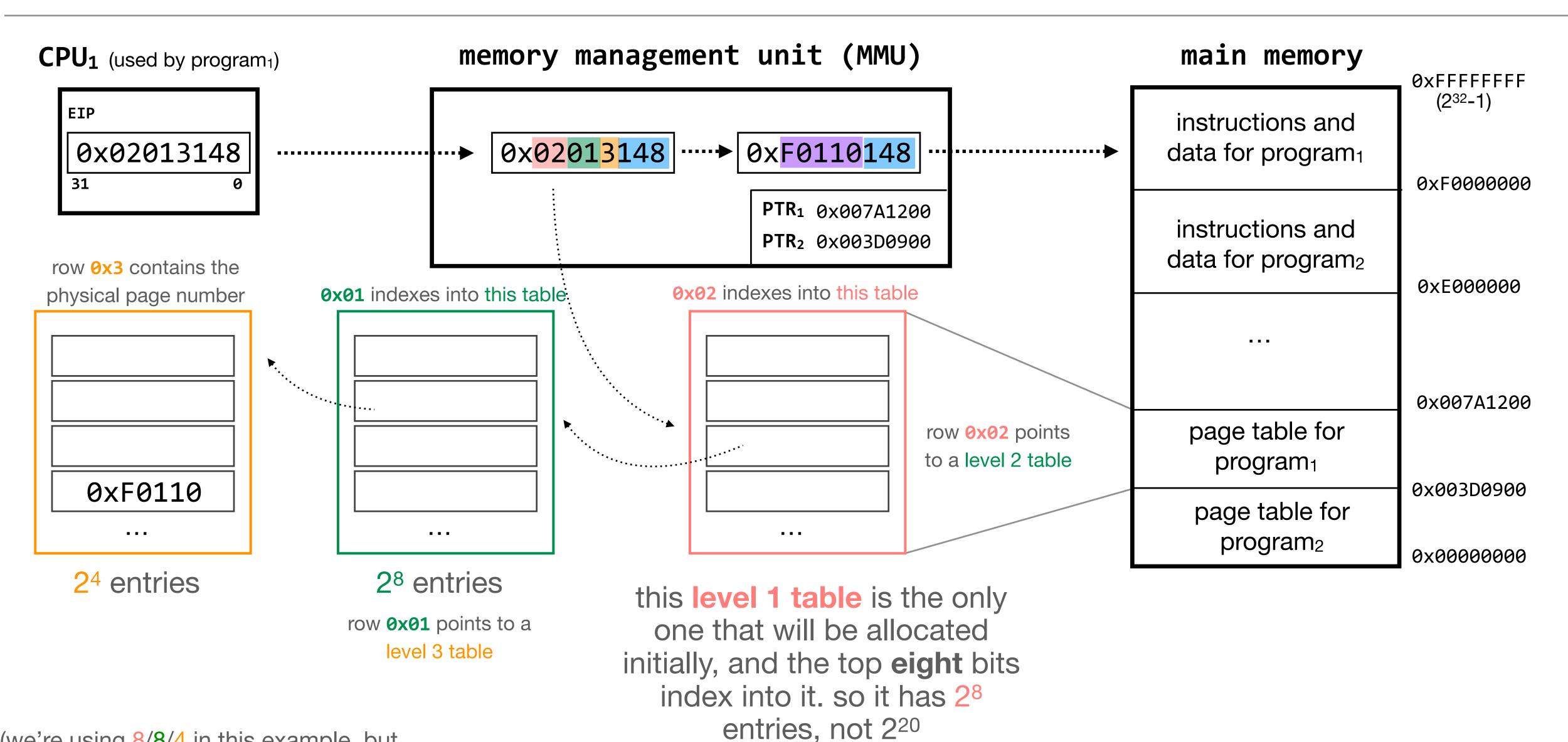
multilevel page tables often use less space

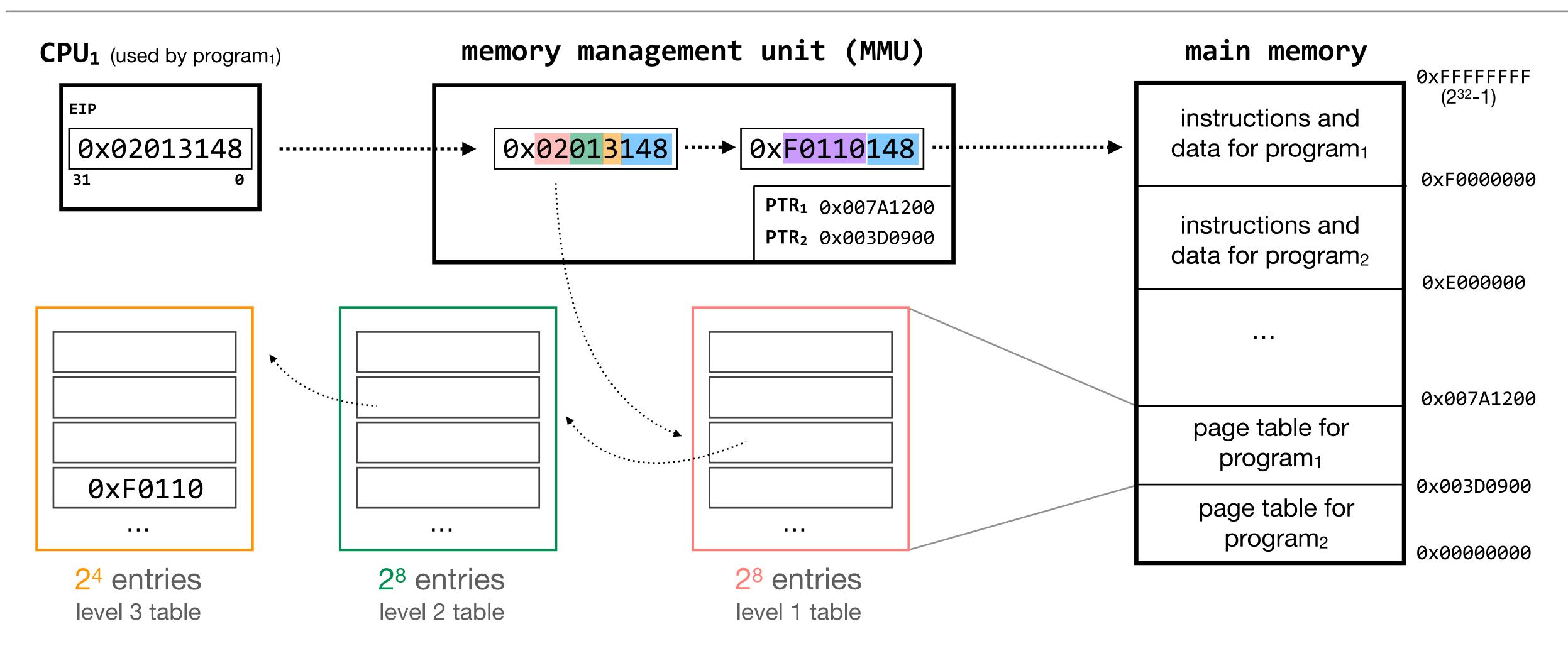


multilevel page tables often use less space



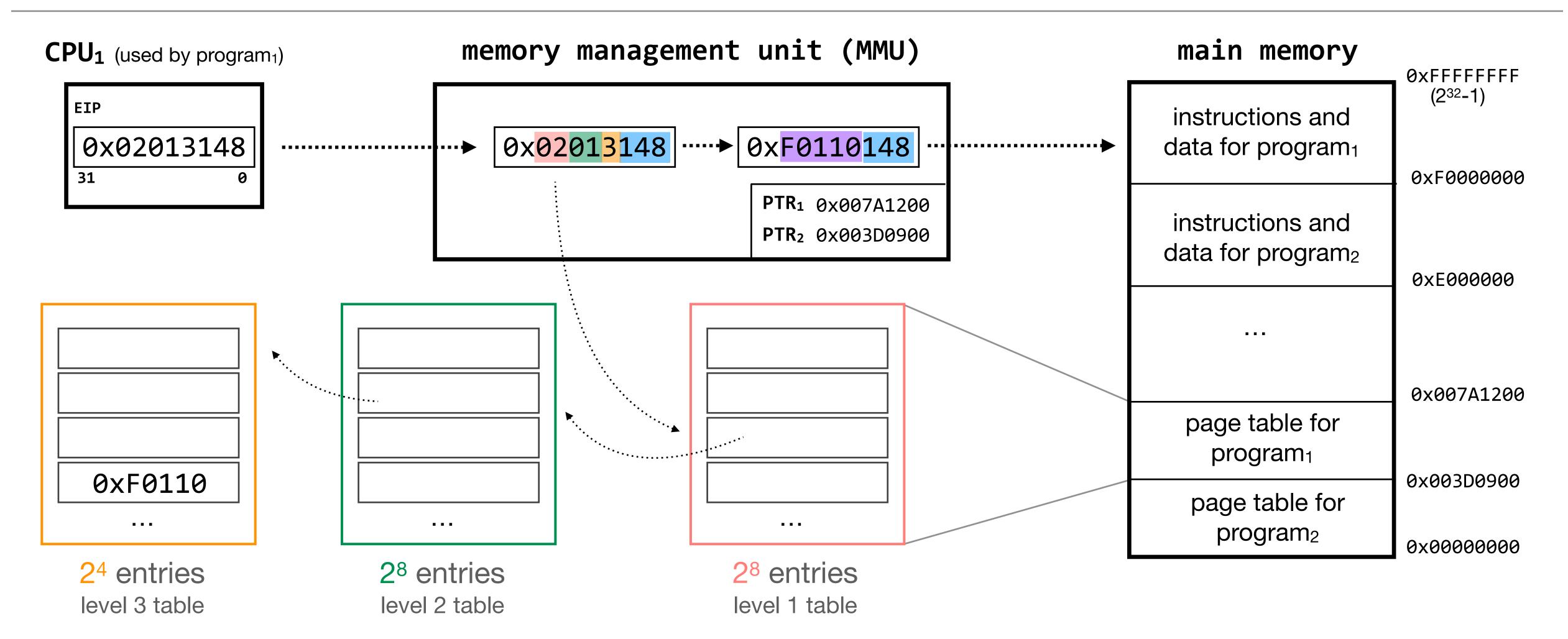
multilevel page tables often use less space



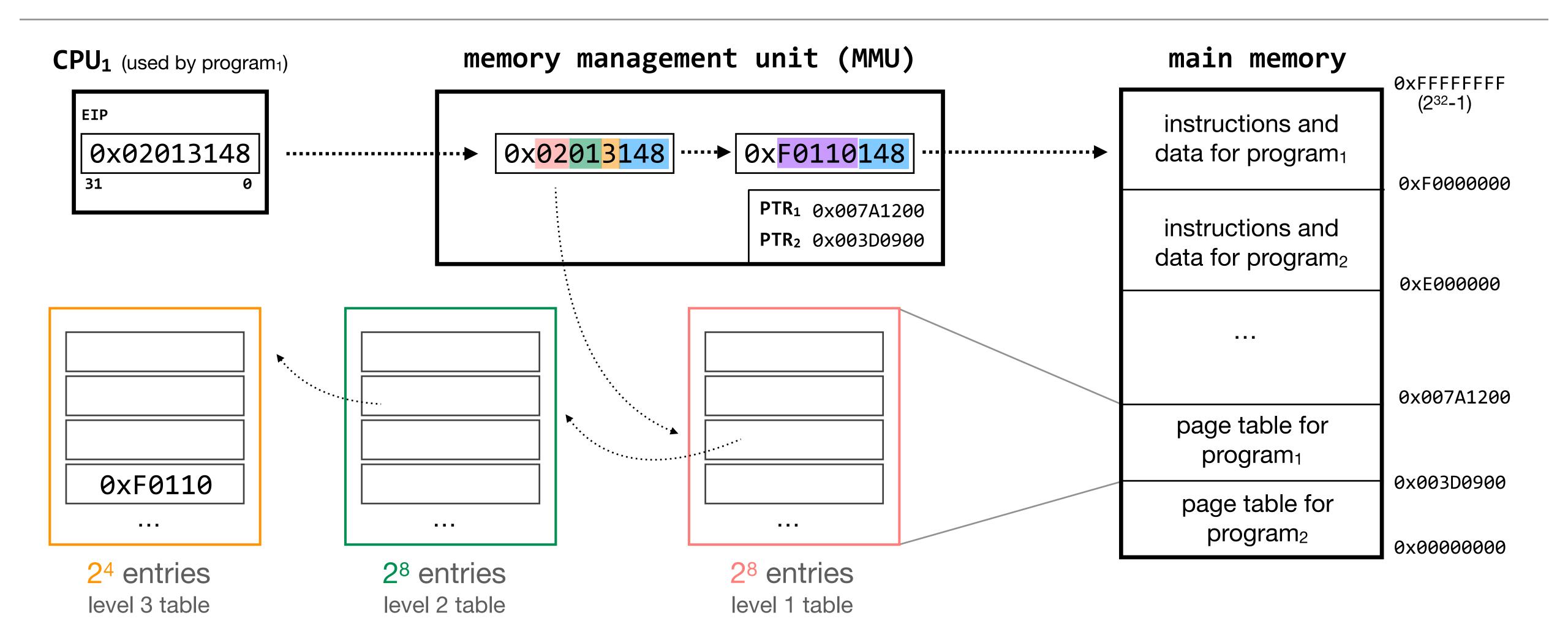


each row in the level 1 table (typically) corresponds to a different level 2 table, but each level 2 table (and level 3 table) is allocated as needed

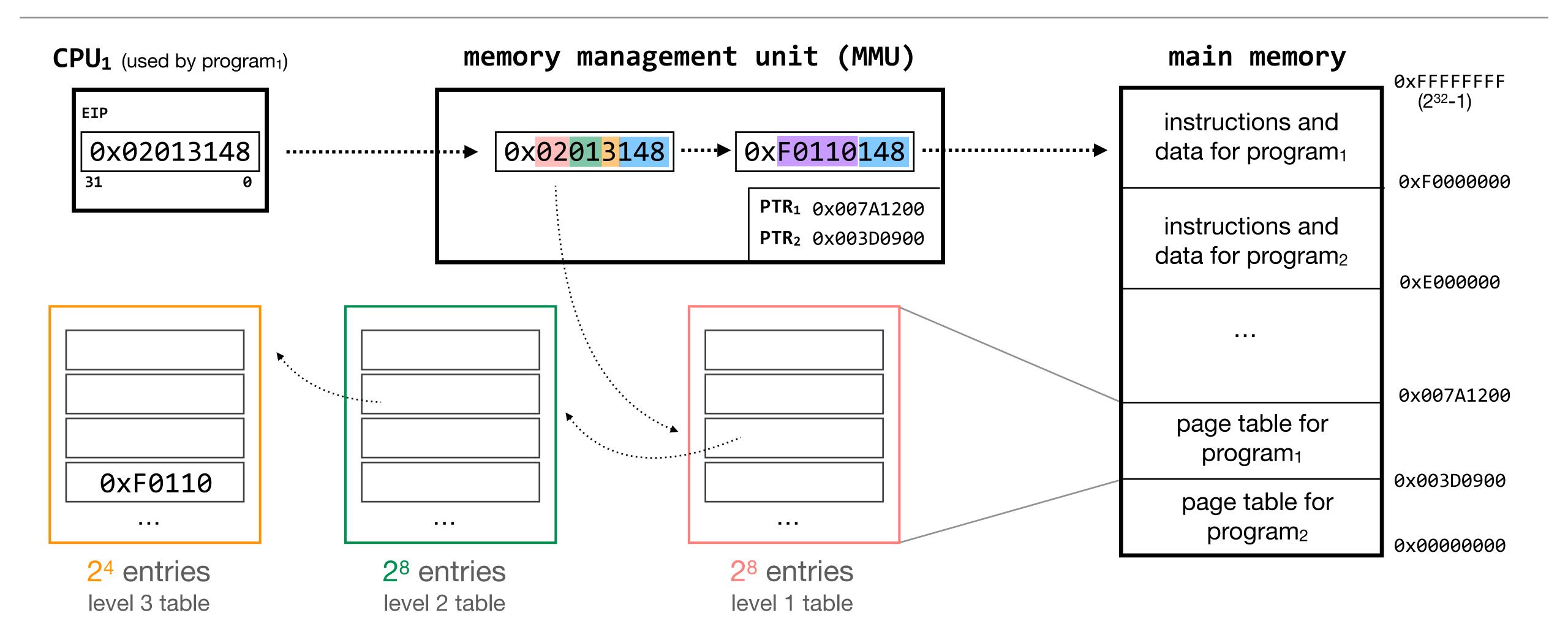
multilevel page tables often use less space, at the expense of more table look-ups and more exceptions (to allocate additional tables)



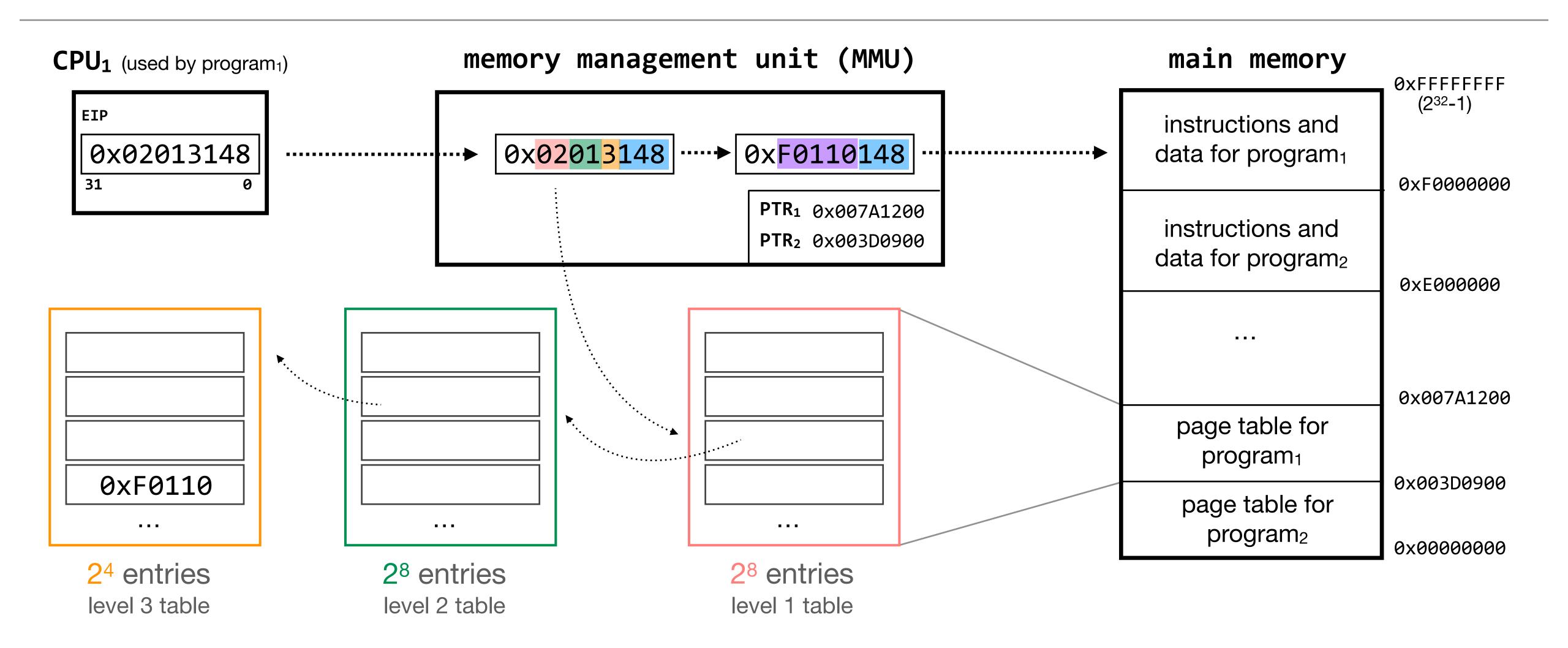
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performance issue #2: looking up the same piece of data over and over again takes time; can we make it faster?



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yes. caches are involved in a variety of places here, to (in theory) make common look-ups faster. you've also seen caching in the context of DNS.

operating systems enforce modularity on a single machine

in order to enforce modularity + have an effective operating system, a few things need to happen

programs shouldn't be able to refer to
 (and corrupt) each others' memory

virtualize **memory**

2. programs should be able to **communicate** with each other

assume they don't need to (for today)

3. programs should be able to **share a CPU** without one program halting the progress of the others

assume one program per CPU (for today)

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 assume one program per CPU

 (for today)

the primary technique that an operating system uses to enforce modularity is **virtualization**. some components are difficult to virtualize (e.g., the disk); for those, the operating system presents **abstractions**

you'll talk much more about abstractions during the recitations on UNIX; designing good abstractions is part of designing a good operating system

virtualizing memory prevents programs from referring to (and corrupting) each other's memory. the **MMU** translates virtual addresses to physical addresses using **page tables**, and there are a number of **performance issues** to take into account

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the **kernel** handles any exceptions triggered in this process; protecting the kernel from user programs is just as important as protecting user programs from each other